



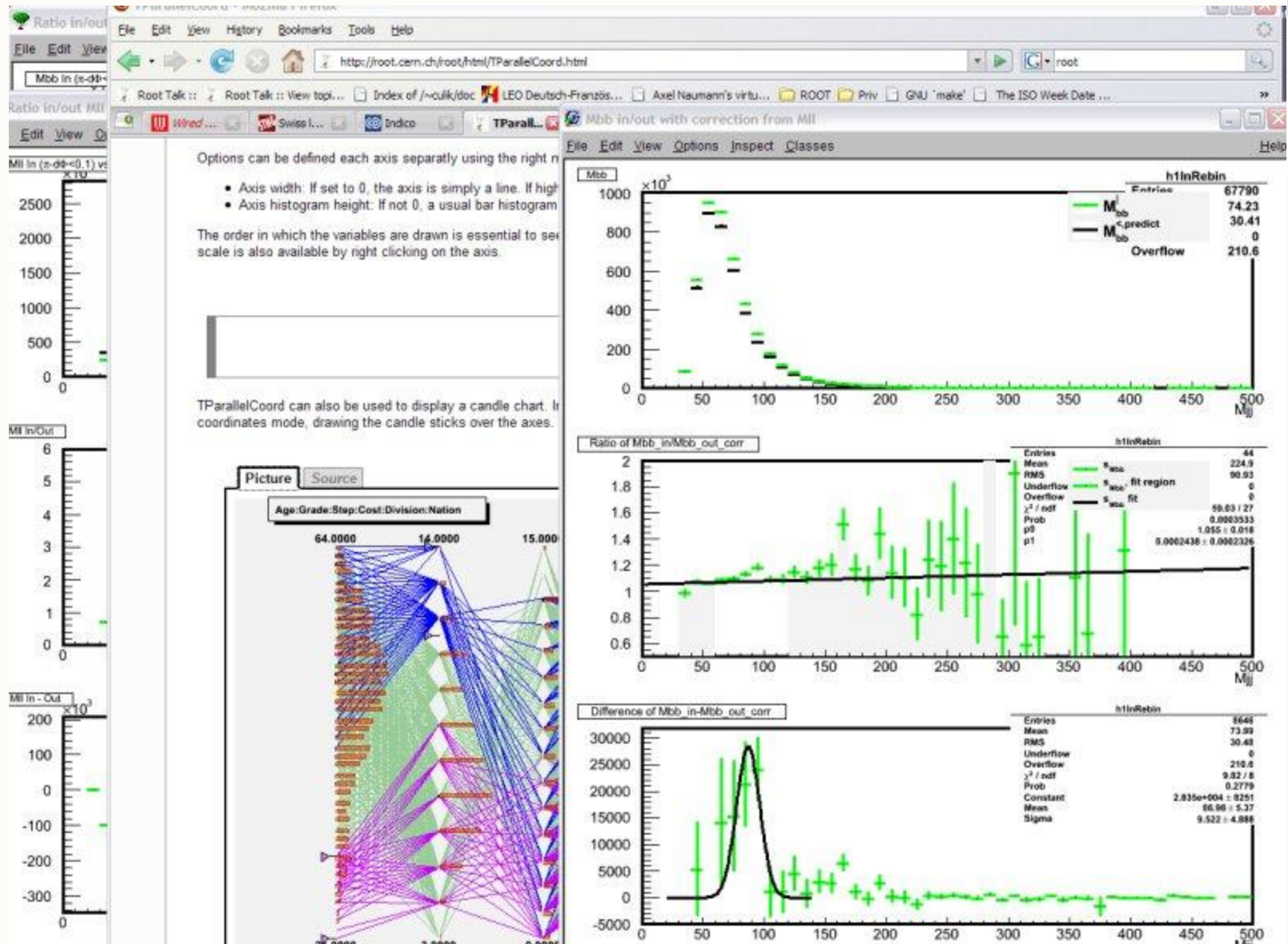
ROOT

Bertrand Bellenot, Axel Naumann

CERN

WHAT IS ROOT?

What's ROOT?





ROOT: An Open Source Project

- Started in 1995
- 7 full time developers at CERN, plus Fermilab
- Large number of part-time developers: let users participate
- Available (incl. source) under GNU LGPL

ROOT in a Nutshell

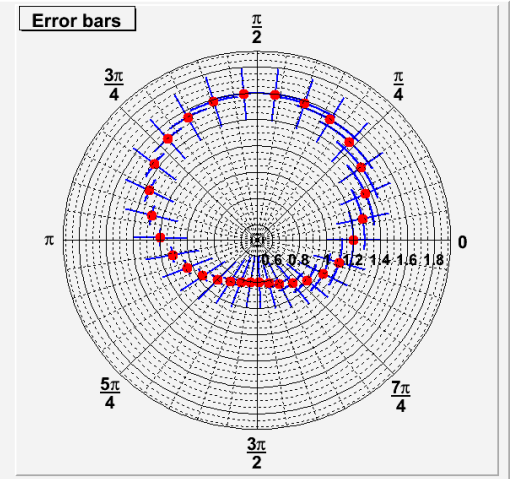
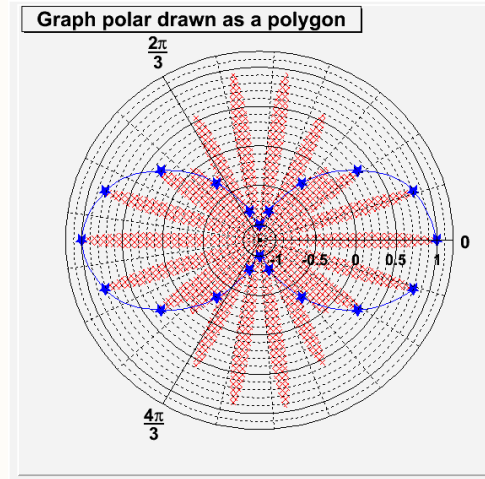
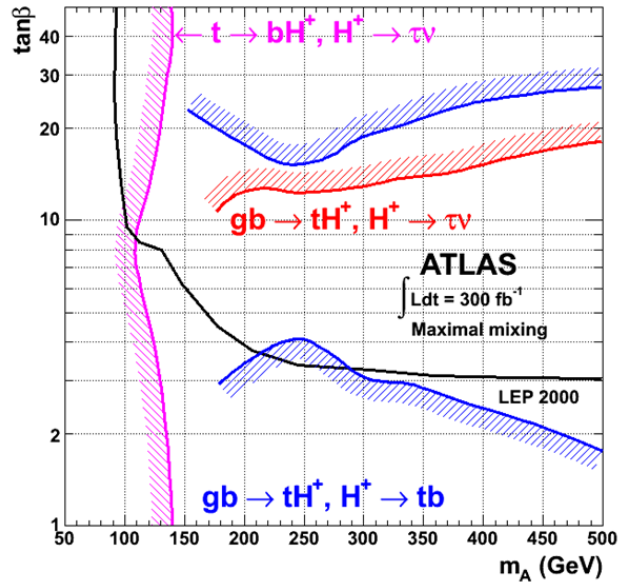


Framework for large scale data handling

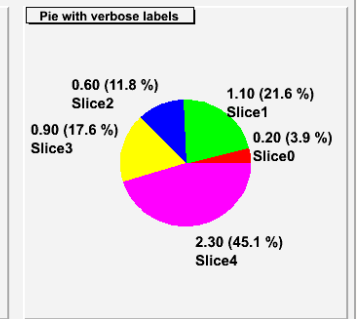
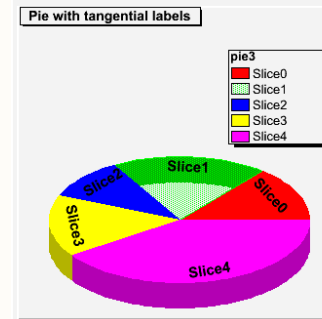
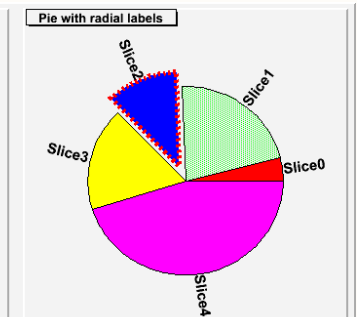
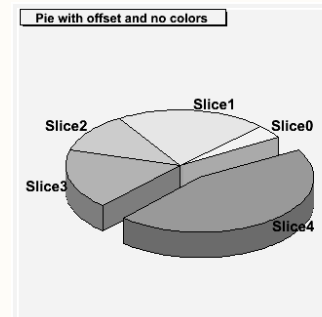
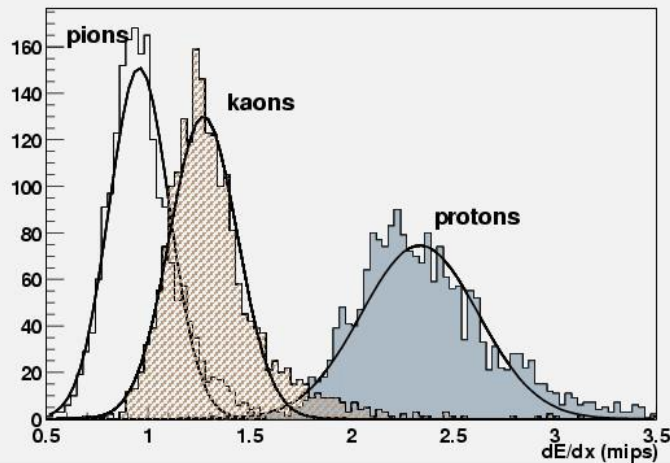
Provides, among others,

- an efficient data storage, access and query system (PetaBytes)
- advanced statistical analysis algorithms (multi dimensional histogramming, fitting, minimization and cluster finding)
- scientific visualization: 2D and 3D graphics, Postscript, PDF, LaTeX
- geometrical modeller
- PROOF parallel query engine

Graphics

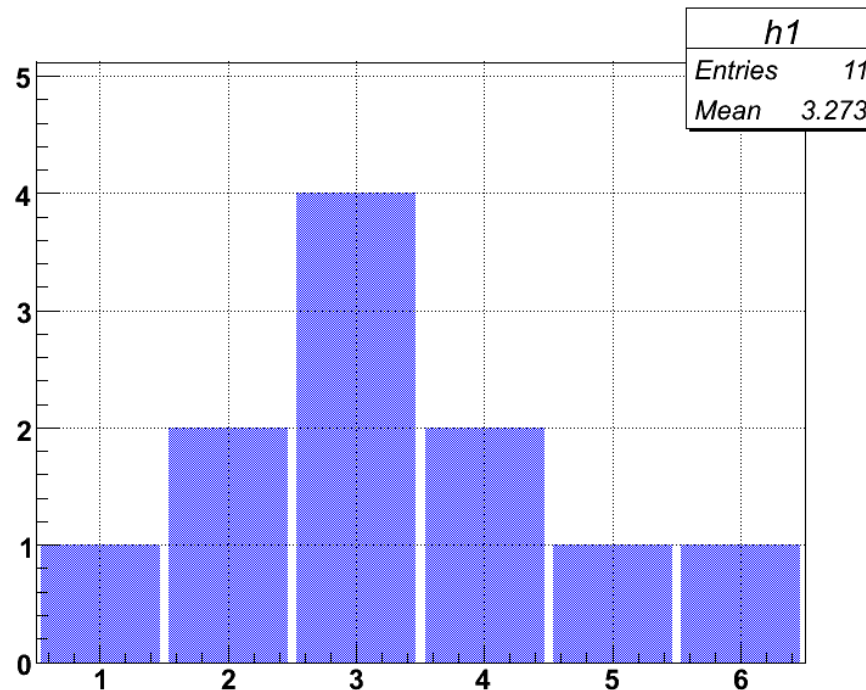


Momentum 730-830 MeV/c



Histogramming

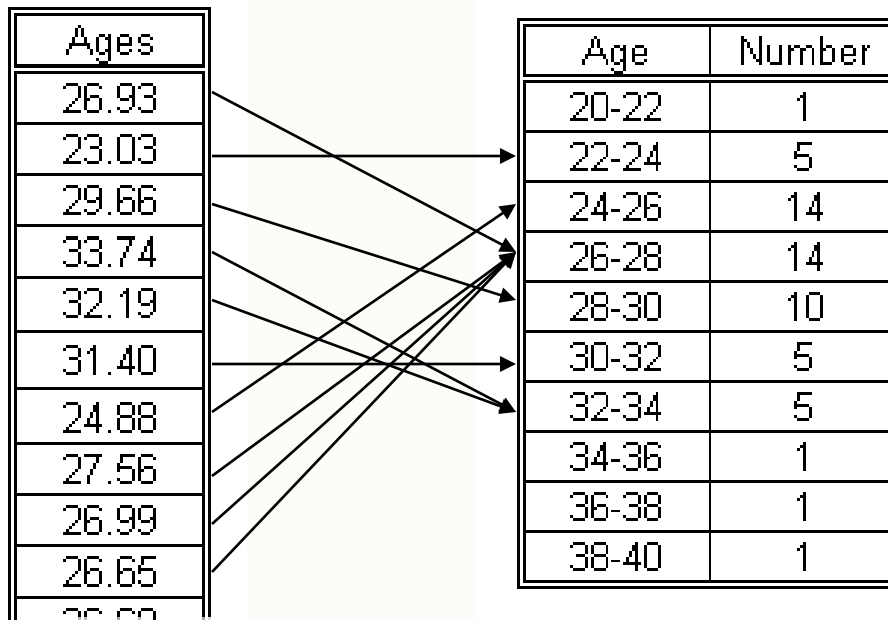
- Histogram is just occurrence counting, i.e. how often they appear
- Example: {1,3,2,6,2,3,4,3,4,3,5}



Histogramming

- **How is a Real Histogram Made?**

Lets consider the age distribution of the CSC participants in 2008:



Binning:

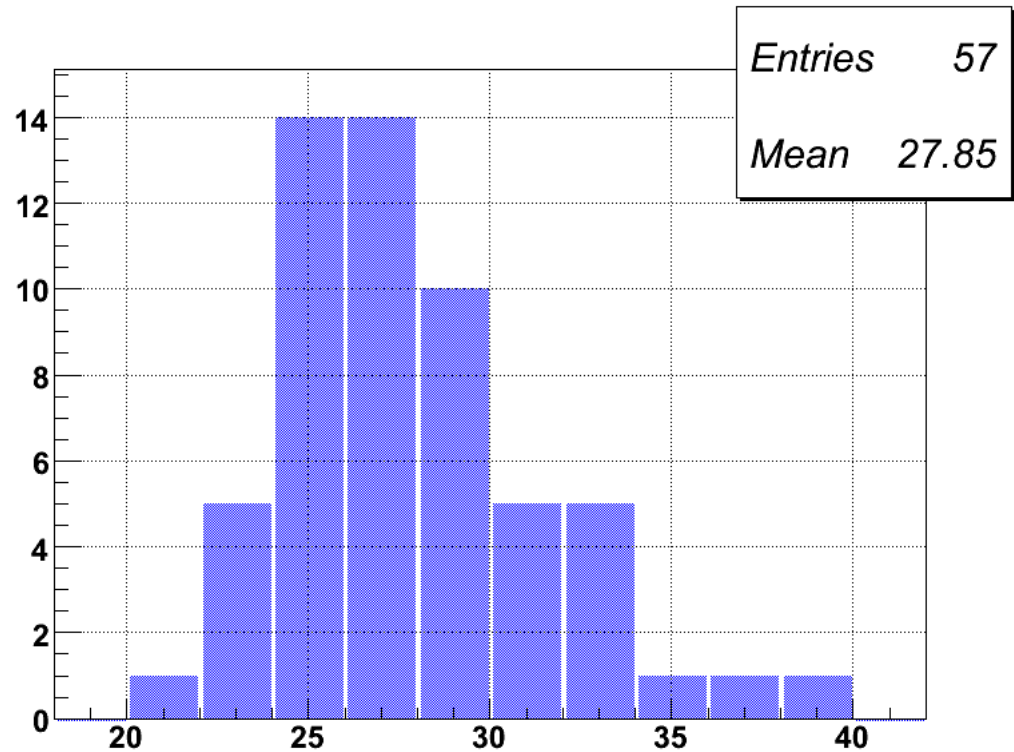
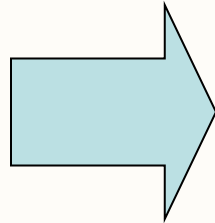
Grouping ages of participants in several categories (bins)

Histogramming



Table of Ages
(binned)

Age	Number
20-22	1
22-24	5
24-26	14
26-28	14
28-30	10
30-32	5
32-34	5
34-36	1
36-38	1
38-40	1



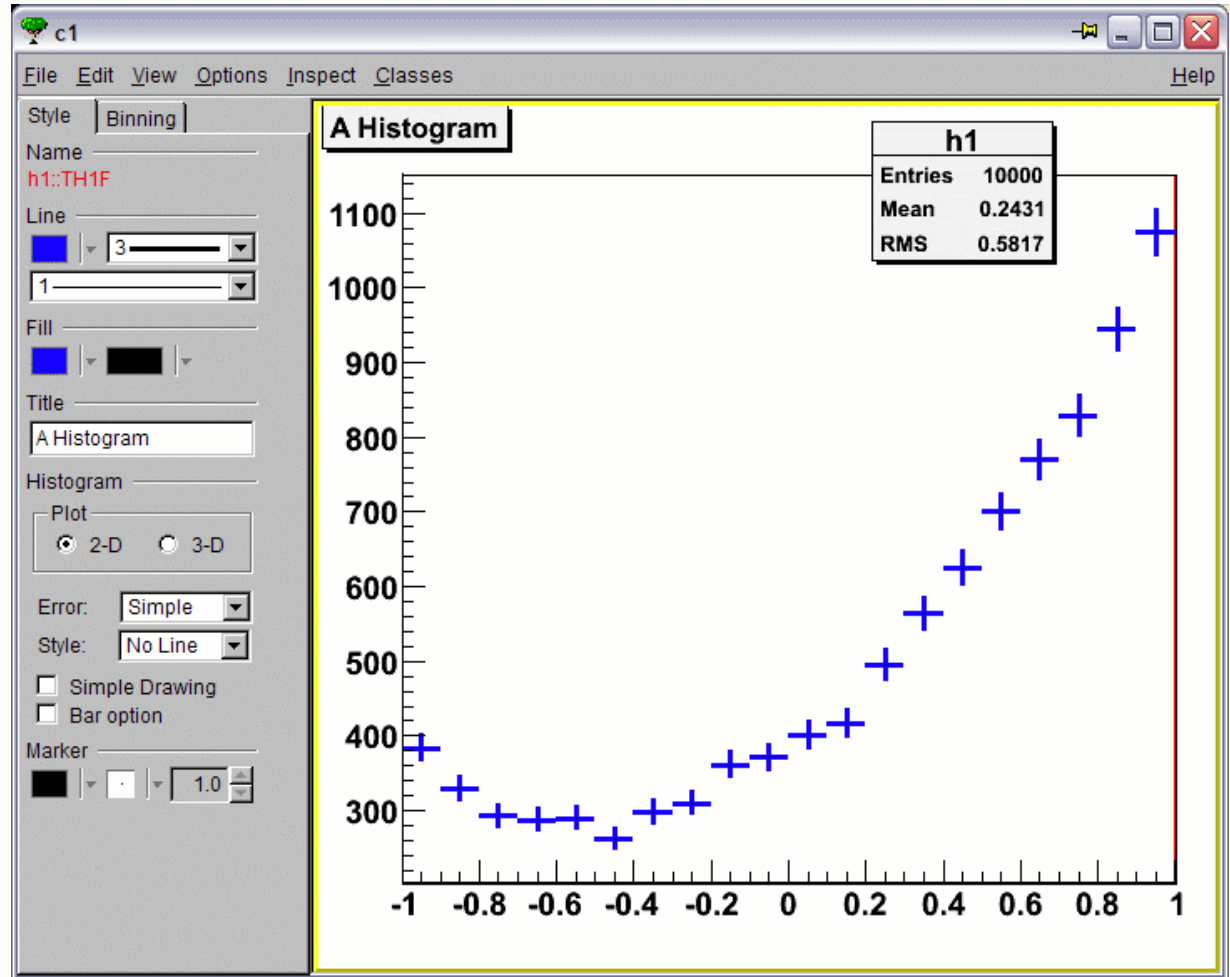
Shows distribution of ages, total number of entries (57 participants) and average: 27 years 10 months 6 days...

Histograms



Analysis result: often a histogram

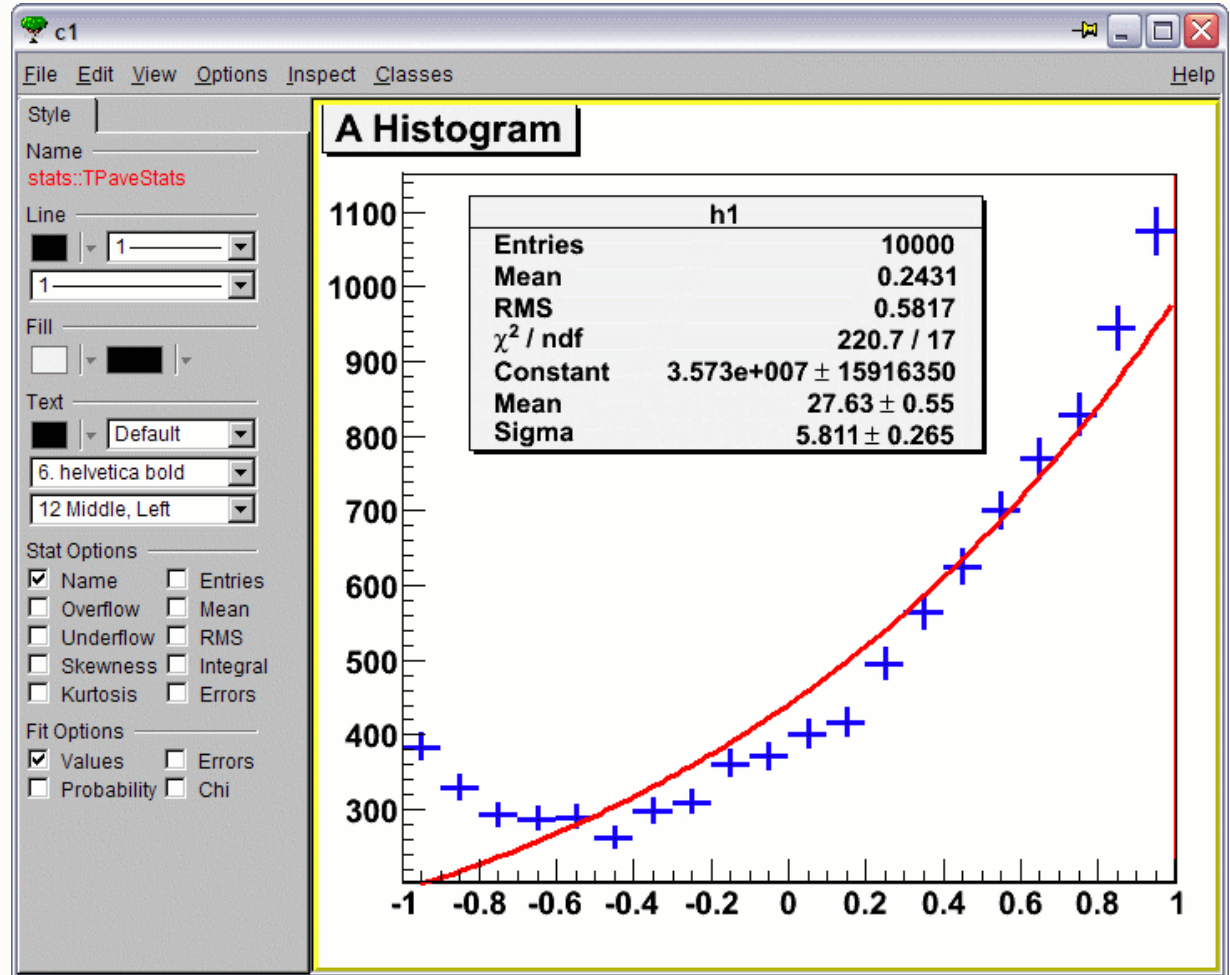
Menu:
View / Editor



Fitting



Analysis result: often a *fit* of a histogram

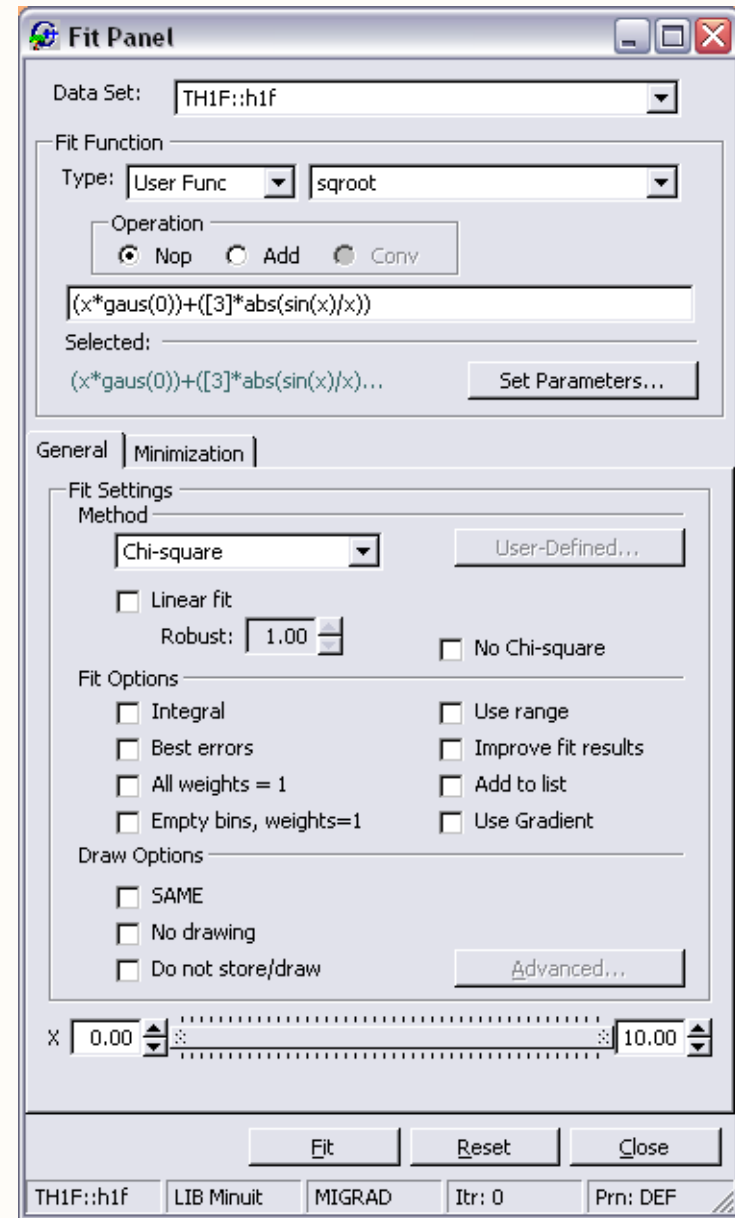


Fit Panel



To fit a histogram:
right click histogram,
"Fit Panel"

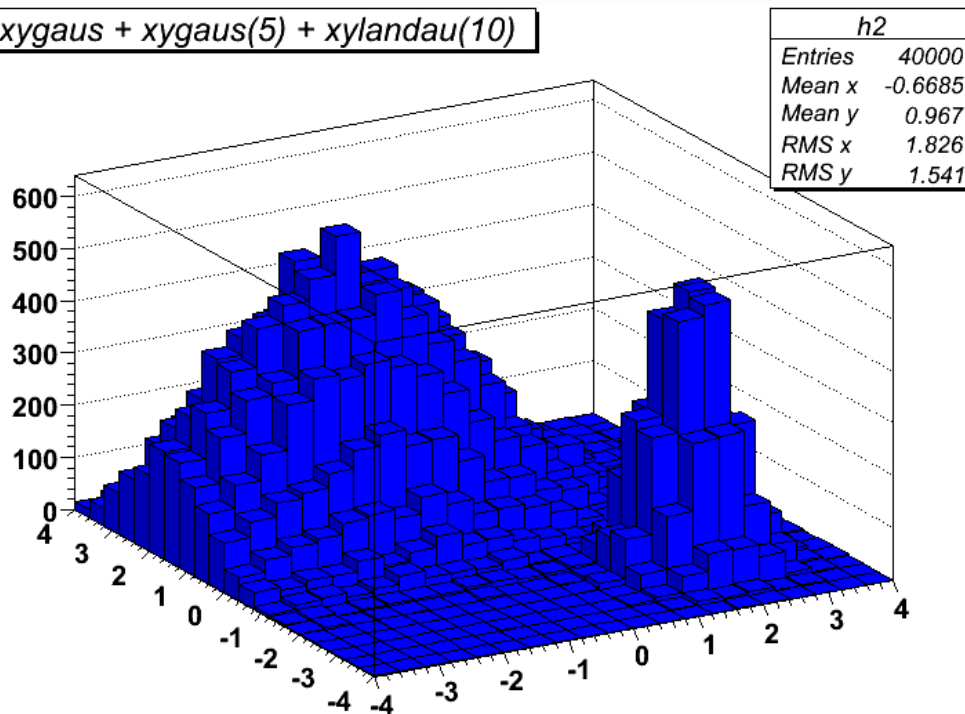
Straightforward interface
for fitting!



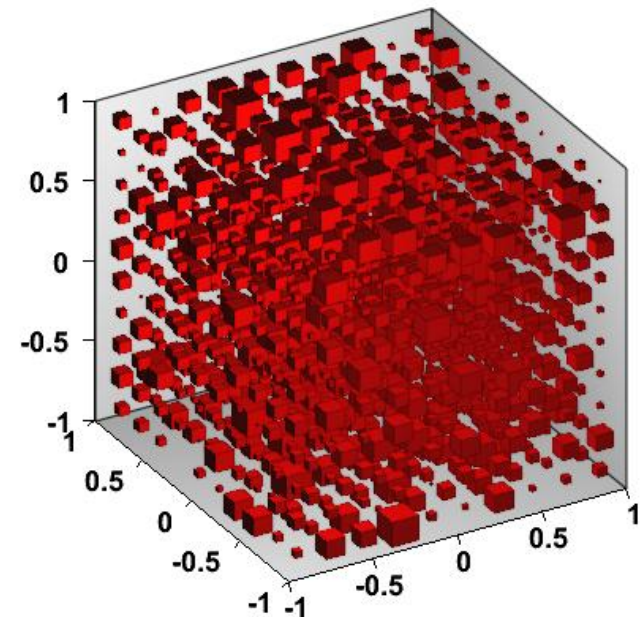
2D/3D

We have seen 1D histograms, but there are also histograms in more dimensions.

`xygaus + xygaus(5) + xylandau(10)`



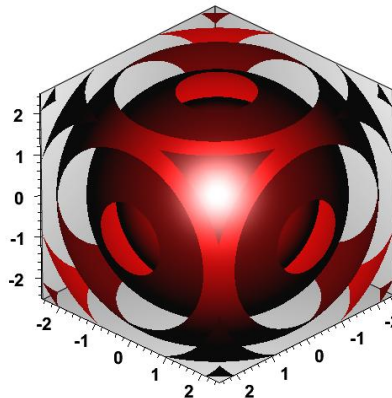
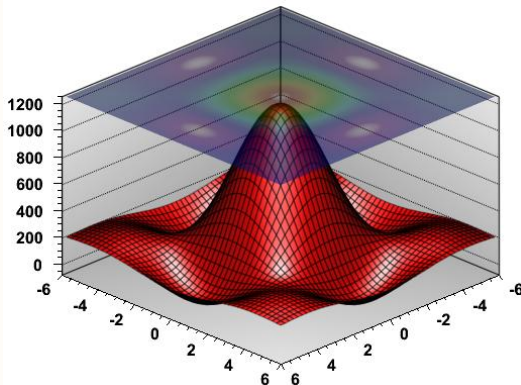
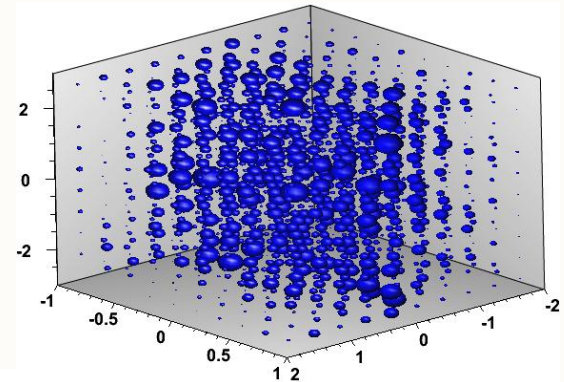
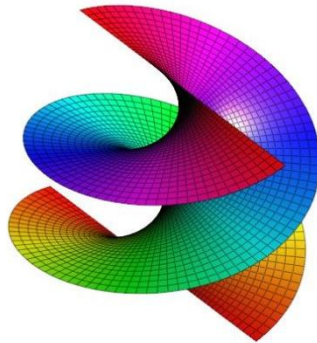
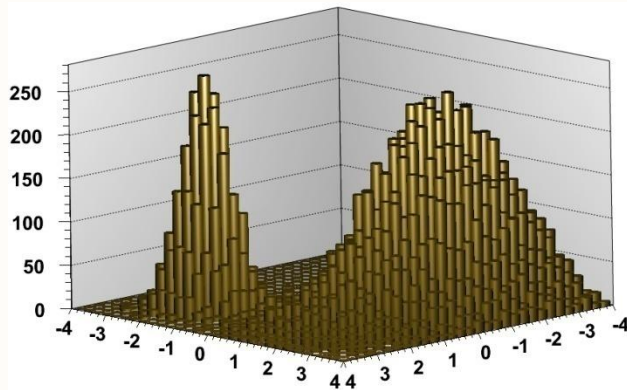
2D Histogram



3D Histogram

OpenGL

OpenGL can be used to render 2D & 3D histograms, functions, parametric equations, and to visualize 3D objects (geometry)

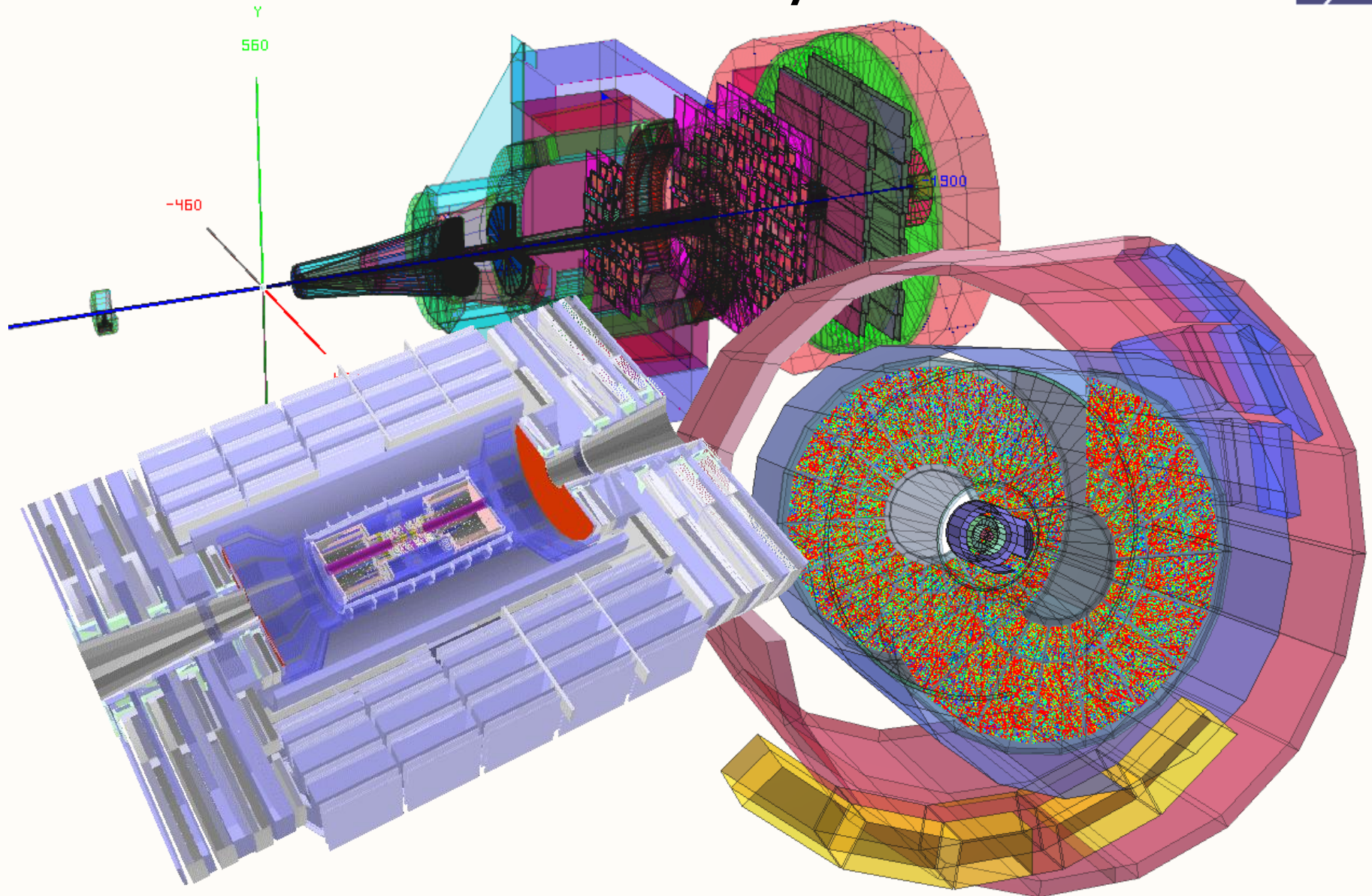


Geometry



- Describes complex detector geometries
- Allows visualization of these detector geometries with e.g. OpenGL
- Optimized particle transport in complex geometries
- Working in correlation with simulation packages such as GEANT₃, GEANT₄ and FLUKA

Geometry



EVE (Event Visualization Environment)

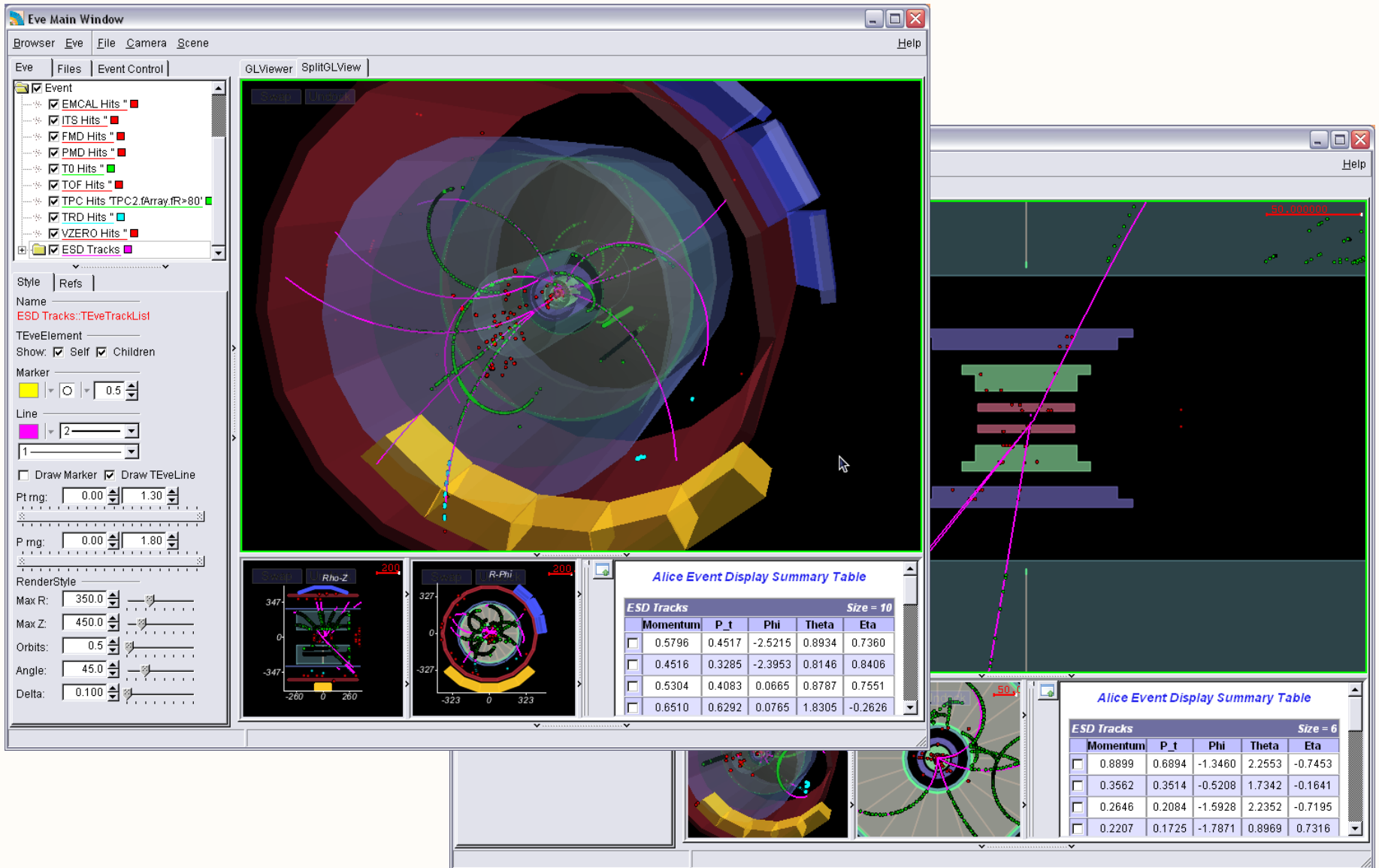


- Event: Collection of data from a detector (hits, tracks, ...)

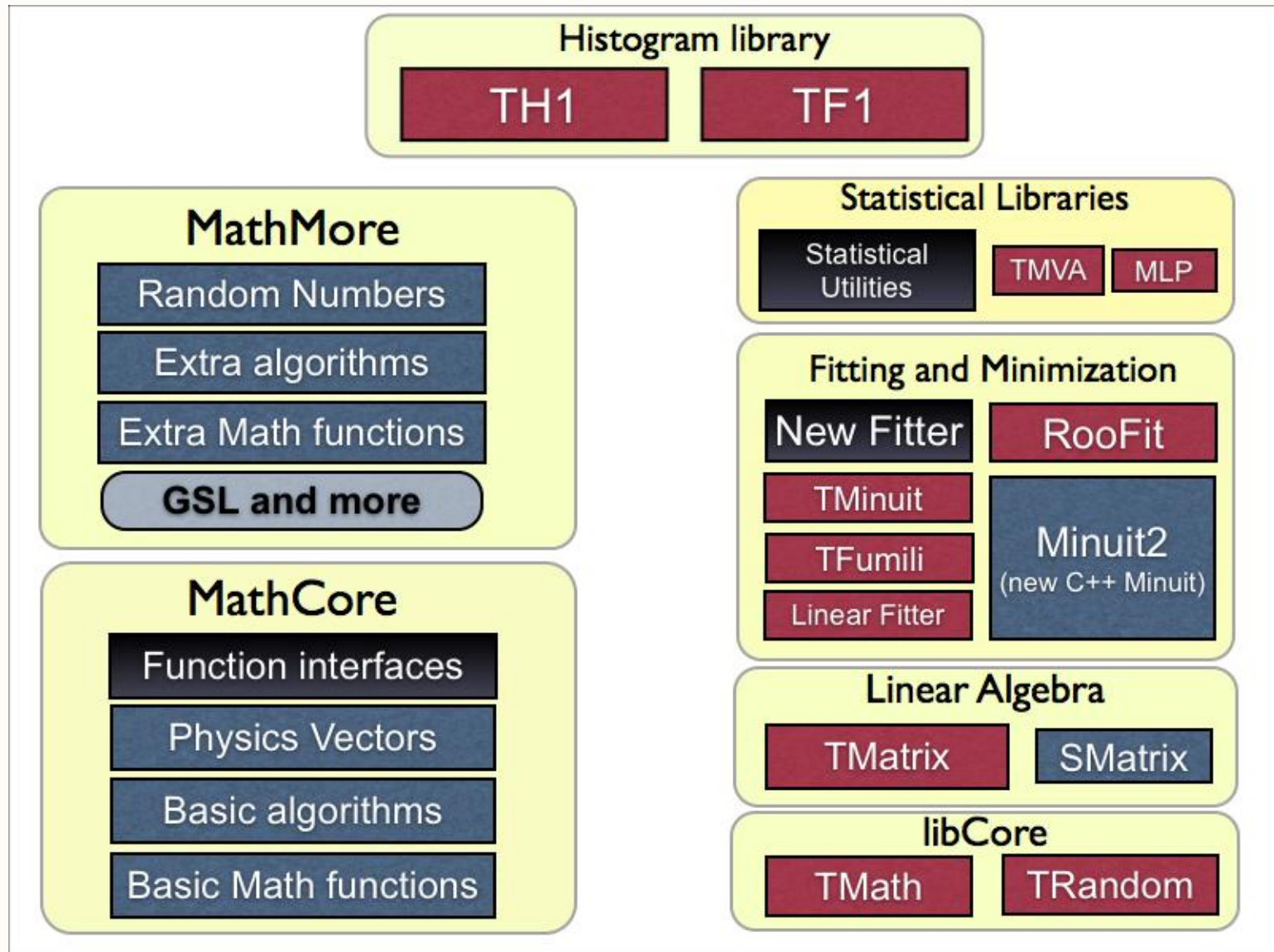
Use EVE to:

- Visualize these physics objects together with detector geometry (OpenGL)
- Visually interact with the data, e.g. select a particular track and retrieve its physical properties

EVE



Math



Math Example:

RANDOM NUMBERS

Quasi-Random Numbers



- Needed e.g. to simulate nature: will particle interact?
- Trivial example for random number generator function:
last digit of $n = n + 7$,
say start with 0:
0, 7, 4, 1, 8, 5, 2, 9, 6, 3, 0, 7, 4, 1, 8, 5, 2, 9, 6, 3, 0, 7, 4, 1, 8,
- Properties:
 - identical frequency of all numbers 0..9
 - “looks” random, but short period:
0, 7, 4, 1, 8, 5, 2, 9, 6, 3, 0, 7, 4, 1, 8, 5, 2, 9, 6, 3, 0, 7, 4, 1
 - numbers not independent!

Random Number Generator

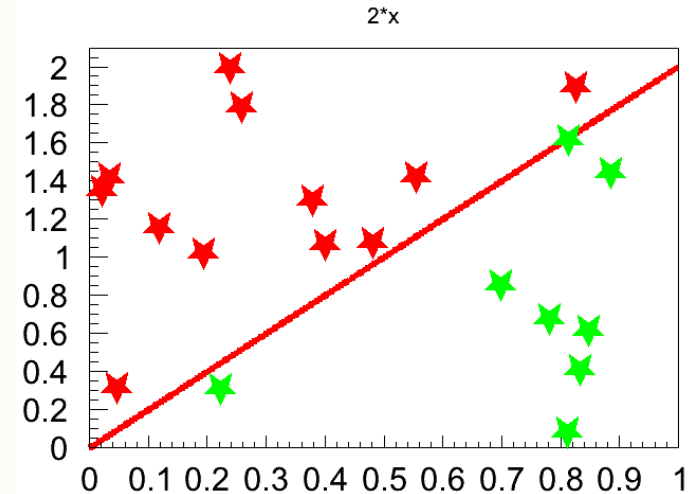


- Solution: more complex function
 - Mersenne Twister (TRandom3) is recommended
- ```
TRandom3 myRnd; myRnd.Uniform();
```
- generates random number between  $>0$  and  $\leq 1$
- period  $10^{6000}$ , fast!
- Flat probability distribution function good for dice, usually not for physics:
  - measurement uncertainty: gaussian
  - particle lifetime:  $N(t) = N_0 \exp(-t/\tau)$  i.e. exponential
  - energy loss of particles in matter: landau

# Naïve Random Distribution



- Want to “sample” distribution  
 $y = 2x$  for  $0 < x < 1$
- Acceptance-rejection method
- Generate random  $x^*$  and  $y^*$  point:  
if  $y^* \leq 1 - x^2$ , return as random  
number, else generate new  $x^*, y^*$ .

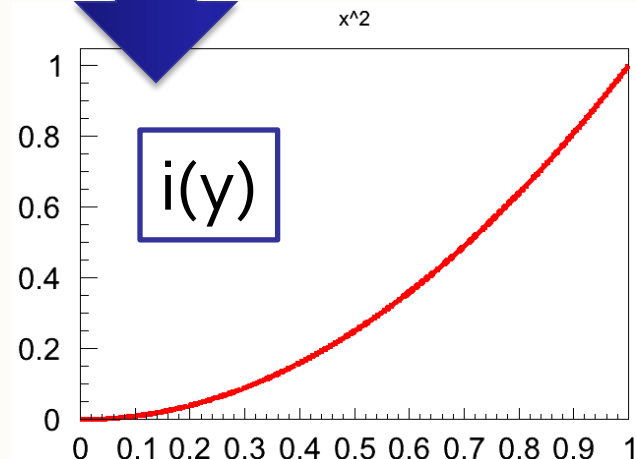
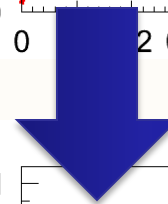
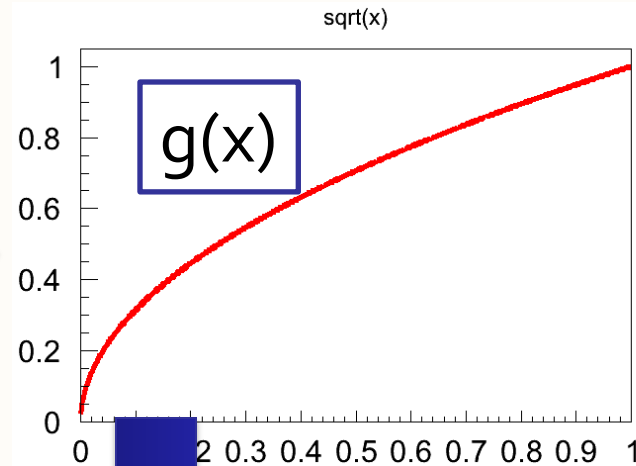
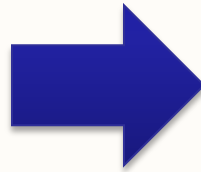
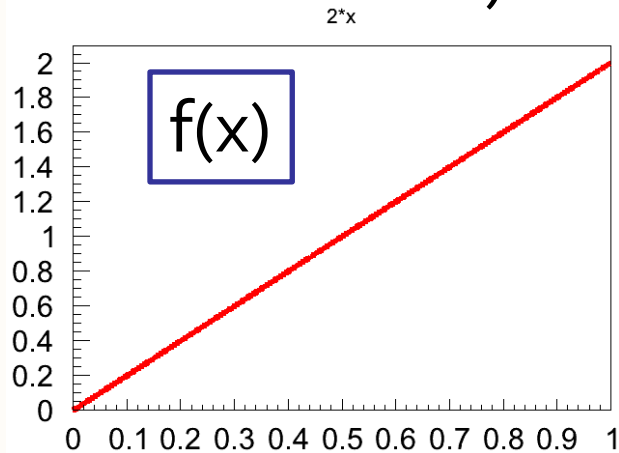


- Problem: waste of CPU, especially if function evaluation costs a lot of CPU time

# Random Distribution From Inverse



- Integral  $g(x)$  of distribution  $f(x)$  (probability density function "PDF"):



- and inverse  $i(y)$  of  $g(x)$
- random number  $0 < y^* < 1$
- return  $i(y^*)$
- $i(y^*)$  is distributed like  $f(x)$



# Smart Random Distribution



- Problem with inverse: must be known!
- Can combine rejection on  $f()$  and inverse of  $a()$  and  $b()$  with  $a(x) \leq f(x) \leq b(x)$  to reduce sampling overhead
- ROOT implements *fast* generators for random numbers distributed like Gauss, exp, Landau, Poisson...

# Interlude: HELP!



ROOT is a framework – only as good as its documentation.

<http://root.cern.ch>

- User's Guide (it has your answers!)
- Reference Guide

What is TRandom?

What functions does it have?



# LET'S FIRE UP ROOT!

# Setting Up ROOT



Before starting ROOT:

setup environment variables \$PATH,  
\$LD\_LIBRARY\_PATH

(ba)sh:

```
$ source /PathToRoot/bin/thisroot.sh
```

(t)csh:

```
$ source /PathToRoot/bin/thisroot.csh
```

# Starting Up ROOT



ROOT is prompt-based

```
$ root
root [0] _
```

Prompt speaks C++

```
root [0] gROOT->GetVersion();
(const char* 0x5ef7e8)"5.27/04"
```

# ROOT As Pocket Calculator



Calculations:

```
root [0] sqrt(42)
(const double)6.48074069840786038e+00
root [1] double val = 0.17;
root [2] sin(val)
(const double)1.69182349066996029e-01
```

Uses C++ Interpreter CINT

# Running Code

To run function mycode() in file mycode.C:

```
root [0] .x mycode.C
```

Equivalent: load file and run function:

```
root [0] .L mycode.C
root [1] mycode()
```

Quit:

```
root [0] .q
```

All of CINT's commands (help):

```
root [0] .h
```

# ROOT Prompt



- ? Why C++ and not a scripting language?!
- ! You'll write your code in C++, too. Support for python, ruby,... exists.
- ? Why a prompt instead of a GUI?
- ! ROOT is a programming framework, not an office suite. Use GUIs where needed.



# Running Code



Macro: file that is interpreted by CINT (**.x**)

```
int mymacro(int value)
{
 int ret = 42;
 ret += value;
 return ret;
}
```

Execute with **.x mymacro.C(42)**

# Compiling Code: ACLiC



Load code as shared lib, much faster:

```
.x mymacro.C+(42)
```

Uses the system's compiler, takes seconds

Subsequent **.x mymacro.C+(42)** check for changes,  
only rebuild if needed

Exactly as fast as e.g. Makefile based stand-alone binary!

CINT knows types, functions in the file, e.g. call

```
mymacro(43)
```

# Compiled versus Interpreted



? Why compile?

! Faster execution, CINT has limitations, validate code.

? Why interpret?

! Faster Edit → Run → Check result → Edit cycles ("rapid prototyping").

Scripting is sometimes just easier.

? Are Makefiles dead?

! Yes! ACLiC is even platform independent!

# A LITTLE C++

# A Little C++



Hopefully many of you know – but some don't.

- Object, constructor, assignment
- Pointers
- Scope, destructor
- Stack vs. heap
- Inheritance, virtual functions

If you use C++ you *have* to understand these concepts!

# Objects, Constructors, =



Look at this code:

```
TNamed myObject("name", "title");
TNamed mySecond;
mySecond = myObject;
cout << mySecond.GetName() << endl;
```

# Objects, Constructors, =



Look at this code:

```
TNamed myObject("name", "title");
TNamed mySecond;
mySecond = myObject;
cout << mySecond.GetName() << endl;
```

Creating objects:

1. Constructor **TNamed::TNamed(const char\*, const char\*)**
2. Default constructor **TNamed::TNamed()**

# Objects, Constructors, =

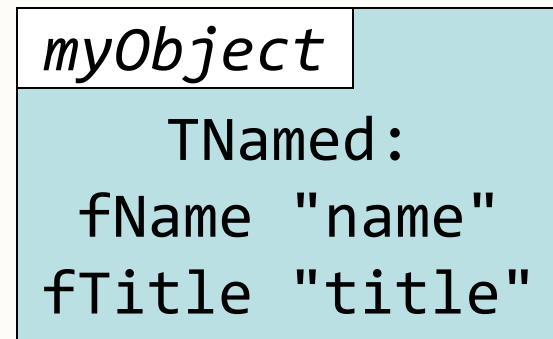
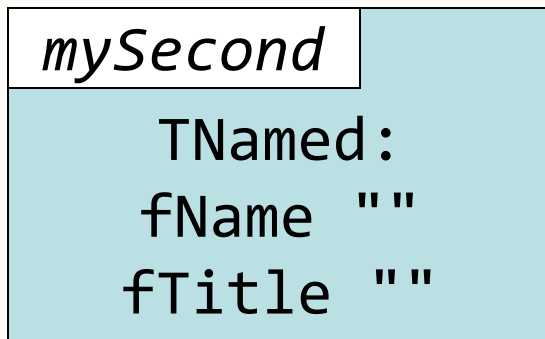


Look at this code:

```
TNamed myObject("name", "title");
TNamed mySecond;
mySecond = myObject;
cout << mySecond.GetName() << endl;
```



3. Assignment:





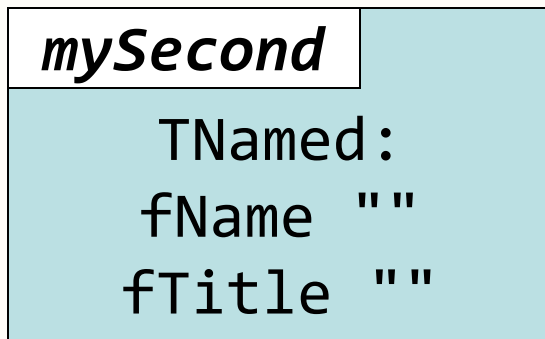
# Objects, Constructors, =



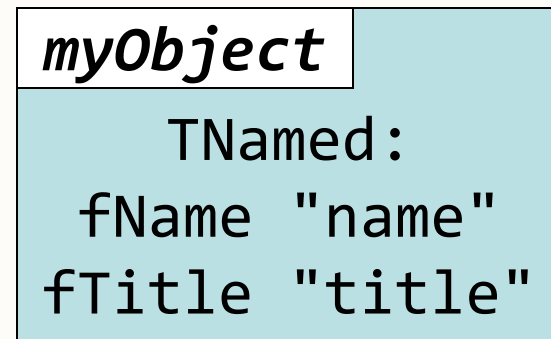
Look at this code:

```
TNamed myObject("name", "title");
TNamed mySecond;
mySecond = myObject;
cout << mySecond.GetName() << endl;
```

3. Assignment: creating a twin



=



# Objects, Constructors, =



Look at this code:

```
TNamed myObject("name", "title");
TNamed mySecond;
mySecond = myObject;
cout << mySecond.GetName() << endl;
```

4. New content

|                                           |
|-------------------------------------------|
| <i>mySecond</i>                           |
| TNamed:<br>fName "name"<br>fTitle "title" |


output:

"name"

# Pointers

Modified code:

```
TNamed myObject("name", "title");
TNamed* pMySecond = 0;
pMySecond = &myObject;
cout << pMySecond->GetName() << endl;
```



Pointer declared with "\*", initialize to 0

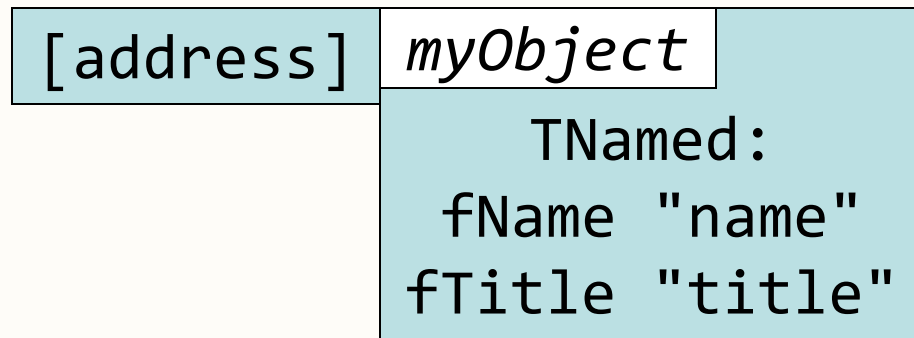
# Pointers

Modified code:

```
TNamed myObject("name", "title");
TNamed* pMySecond = 0;
pMySecond = &myObject;
cout << pMySecond->GetName() << endl;
```

"&" gets address:

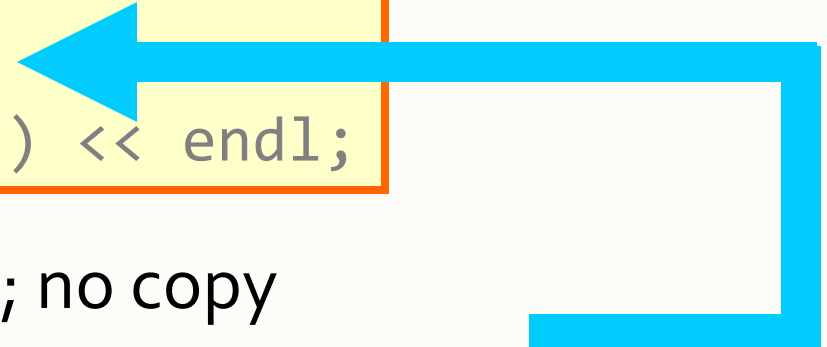
*pMySecond*



# Pointers

Modified code:

```
TNamed myObject("name", "title");
TNamed* pMySecond = 0;
pMySecond = &myObject;
cout << pMySecond->GetName() << endl;
```



Assignment: point to myObject; no copy

|                  |
|------------------|
| <i>pMySecond</i> |
| [address]        |

= &

|                                           |
|-------------------------------------------|
| <i>myObject</i>                           |
| TNamed:<br>fName "name"<br>fTitle "title" |

# Pointers

Modified code:

```
TNamed myObject("name", "title");
TNamed* pMySecond = 0;
pMySecond = &myObject;
cout << pMySecond->GetName() << endl;
```



Access members of value pointed to by "->"

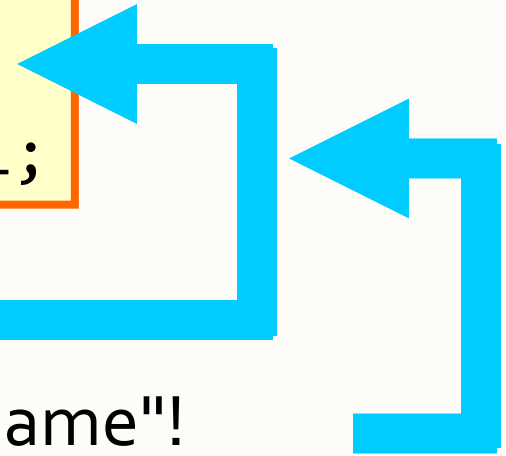
# Pointers

Changes propagated:

```
TNamed myObject("name", "title");
TNamed* pMySecond = 0;
pMySecond = &myObject;
pMySecond->SetName("newname");
cout << myObject.GetName() << endl;
```

Pointer forwards to object

Name of object changed – prints "newname"!



# Object vs. Pointer

Compare object:

```
TNamed myObject("name", "title");
TNamed mySecond = myObject;
cout << mySecond.GetName() << endl;
```

to pointer:

```
TNamed myObject("name", "title");
TNamed* pMySecond = &myObject;
cout << pMySecond->GetName() << endl;
```



# Object vs. Pointer: Parameters



Calling functions: object parameter obj gets copied  
for function  
call!

```
void funcO(TNamed obj);
TNamed myObject;
funcO(myObject);
```

Pointer parameter: only address passed,  
no copy

```
void funcP(TNamed* ptr);
TNamed myObject;
funcP(&myObject);
```

# Object vs. Pointer: Parameters



Functions changing parameter: funcO can only access

copy!

**caller** not  
changed!

```
void funcO(TNamed obj){
 obj.SetName("nope");
}

funcO(caller);
```

Using pointers (or references) funcP can change  
**caller**

```
void funcP(TNamed* ptr){
 ptr->SetName("yes");
}

funcP(&caller);
```

# Scope

Scope: range of visibility and C++ "life".

Birth: constructor, death: destructor

```
{ // birth: TNamed() called
 TNamed n;
} // death: ~TNamed() called
```

Variables are valid / visible only in scopes:

```
int a = 42;
{ int a = 0; }
cout << a << endl;
```

# Scope



Functions are scopes:

```
void func(){ TNamed obj; }

func();
cout << obj << end; // obj UNKNOWN!
```

must not return  
pointers to  
local variables!

```
TNamed* func(){
 TNamed obj;
 return &obj; // BAD!
}
```

# Stack vs. Heap

So far only stack:

```
TNamed myObj("n", "t");
```

Fast, but often < 10MB. Only survive in scope.

Heap: slower, GBs (RAM + swap), creation and destruction managed by user:

```
TNamed* pMyObj = new TNamed("n", "t");
delete pMyObj; // or memory leak!
```

# Stack vs. Heap: Functions



Can return heap objects without copying:

```
TNamed* CreateNamed(){
 // user must delete returned obj!
 TNamed* ptr = new TNamed("n","t");
 return ptr; }
```

ptr gone – but TNamed object still on the heap, address returned!

```
TNamed* pMyObj = CreateNamed();
cout << pMyObj->GetName() << endl;
delete pMyObj; // or memory leak!
```

# Inheritance

Classes "of same kind" can re-use functionality

E.g. plate and bowl are both dishes:

```
class TPlate: public TDish {...};
class TBowl: public TDish {...};
```

Can implement common functions in TDish:

```
class TDish {
public:
 void Wash();
};
```

```
TPlate *a = new TPlate();
a->Wash();
```

# Inheritance: The Base

Use TPlate, TBowl as dishes:

assign pointer of derived to pointer of base "every plate is a dish"

```
TDish *a = new TPlate();
TDish *b = new TBowl();
```

But not every dish is a plate, i.e. the inverse doesn't work.  
And a bowl is totally not a plate!

```
TPlate* p = new TDish(); // NO!
TPlate* q = new TBowl(); // NO!
```



# Virtual Functions



Often derived classes behave differently:

```
class TDish { ...
 virtual bool ForSoup() const;
};
class TPlate: public TDish { ...
 bool ForSoup() const { return false; }
};
class TBowl: public TDish { ...
 bool ForSoup() const { return true; }
};
```

# Pure Virtual Functions



But TDish cannot know! Mark as "not implemented"

```
class TDish { ...
 virtual bool ForSoup() const = 0;
};
```

Only for virtual functions.

Cannot create object of TDish anymore (one function is missing!)

# Calling Virtual Functions



Call to virtual functions evaluated at runtime:

```
void FillWithSoup(TDish* dish) {
 if (dish->ForSoup())
 dish->SetFull();
}
```

Works for any type as expected:

```
TDish* a = new TPlate();
TDish* b = new TBowl();
FillWithSoup(a); // will not be full
FillWithSoup(b); // is now full
```

# Virtual vs. Non-Virtual



So what happens if non-virtual?

```
class TDish { ...
 bool ForSoup() const {return false;}
};
```

Will now always call TDish::ForSoup(), i.e. false

```
void FillWithSoup(TDish* dish) {
 if (dish->ForSoup())
 dish->SetFull();
}
```

# Congrats!



*You have earned yourself the CSC ROOT  
C++ Diploma.*

*From now on you may use C++ without  
feeling lost!*

# Summary



We know:

- why and how to start ROOT
- C++ basics
- that you run your code with ".x"
- can call functions in libraries
- can (mis-) use ROOT as a pocket calculator!

Lots for you to discover during next two lectures and especially the exercises!



Streaming, Reflection, TFile,  
Schema Evolution

# SAVING DATA

# Saving Objects



Cannot do in C++:

```
TNamed* o = new TNamed("name","title");
std::write("file.bin", "obj1", o);
TNamed* p =
 std::read("file.bin", "obj1");
p->GetName();
```

E.g. LHC experiments use C++ to manage data

Need to write C++ objects and read them back

std::cout not an option: 15 PetaBytes / year of processed data (i.e. data that will be read)



# Saving Objects – Saving Types



What's needed?

```
TNamed* o = new TNamed("name", "title");
std::write("file.bin", "obj1", o);
```

Store *data members* of TNamed; need to know:

- 1) type of object
- 2) data members for the type
- 3) where data members are in memory
- 4) read their values from memory, write to disk

# Serialization



Store *data members* of TNamed: **serialization**

1) type of object: **runtime-type-information RTTI**

2) data members for the type: **reflection**

3) where data members are in memory: **introspection**

4) read their values from memory, write to disk: **raw I/O**

Complex task, and C++ is not your friend.

# Reflection

Need type description (aka *reflection*)

1. types, sizes, members

TMyClass is a class.

```
class TMyClass {
 float fFloat;
 Long64_t fLong;
};
```

Members:

- "fFloat", type float, size 4 bytes
- "fLong", type Long64\_t, size 8 bytes

# Platform Data Types



Fundamental data types (int, long,...):  
size is platform dependent

Store "long" on 64bit platform, writing 8 bytes:

00, 00, 00, 00, 00, 00, 00, 42

Read on 32bit platform, "long" only 4 bytes:

00, 00, 00, 00

Data loss, data corruption!

# ROOT Basic Data Types



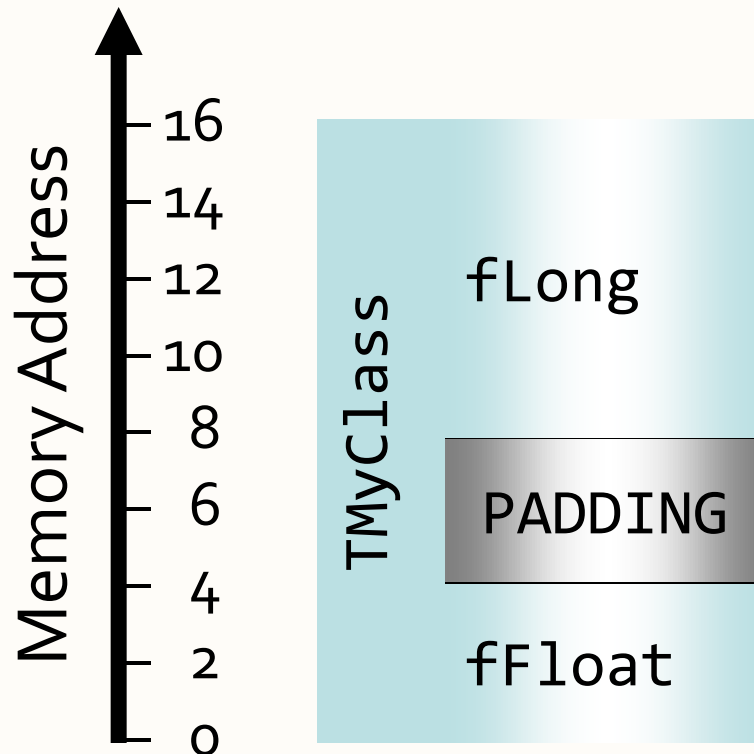
Solution: ROOT typedefs

| Signed     | Unsigned  | sizeof [bytes]                  |
|------------|-----------|---------------------------------|
| Char_t     | UChar_t   | 1                               |
| Short_t    | UShort_t  | 2                               |
| Int_t      | UInt_t    | 4                               |
| Long64_t   | ULong64_t | 8                               |
| Double32_t |           | float on disk, double in<br>RAM |

# Reflection

Need type description (platform dependent)

1. types, sizes, members
2. offsets in memory

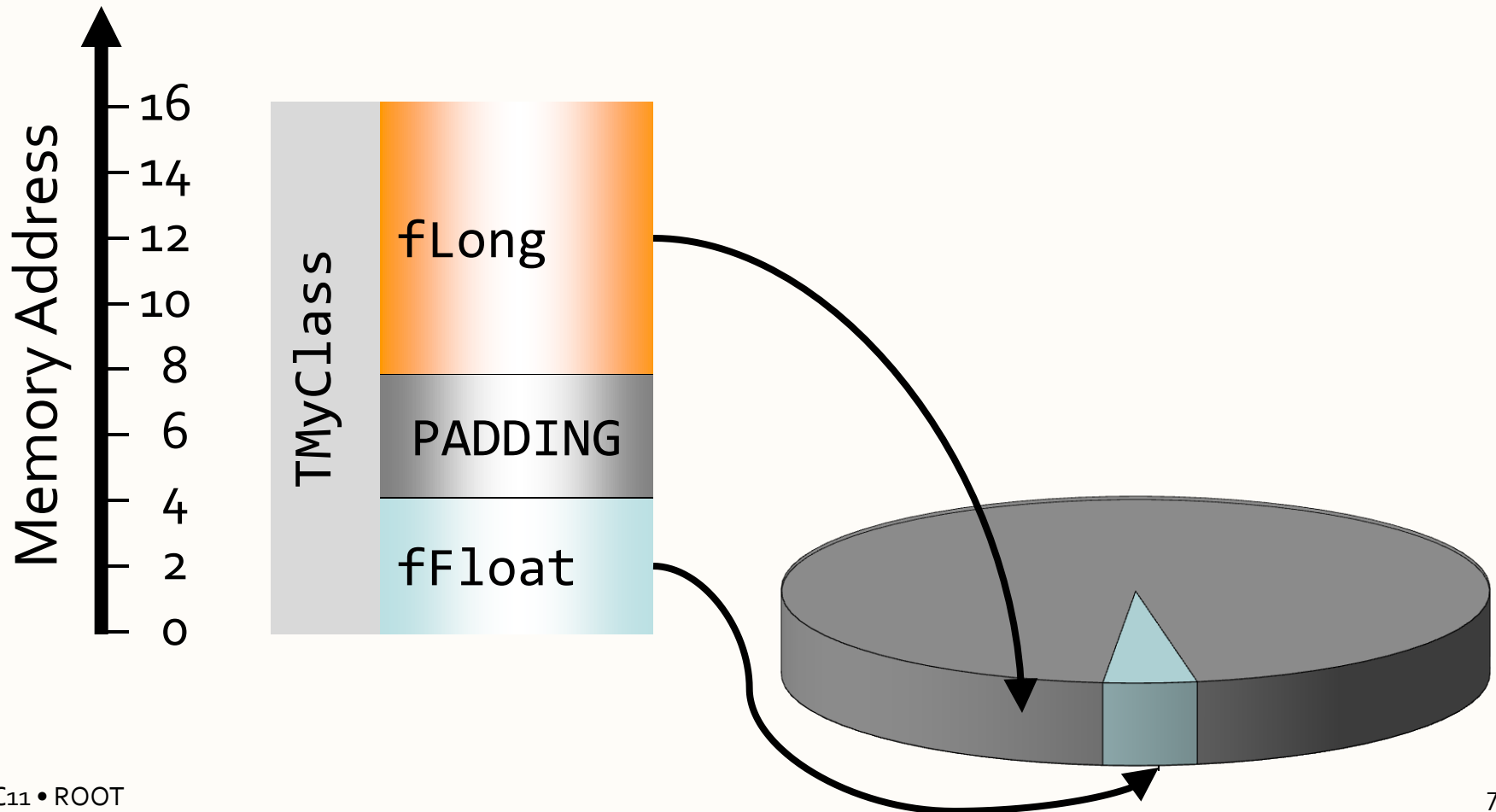


```
class TMyClass {
 float fFloat;
 Long64_t fLong;
};
```

"fFloat" is at offset 0  
 "fLong" is at offset 8

# I/O Using Reflection

members  $\rightarrow$  memory  $\rightarrow$  disk



# C++ Is Not Java



Lesson: need reflection!

Where from?

Java: get data members with

```
Class.forName("MyClass").getFields()
```

C++: get data members with  
– oops. Not part of C++.

**CAREFUL**

**THIS LANGUAGE  
HAS NO BRAIN.  
USE YOUR OWN**



# ROOT And Reflection



Simply use ACLiC:

```
.L MyCode.cxx+
```

Creates library with reflection data ("dictionary") of all types in MyCode.cxx!

Dictionary needed for interpreter, too  
ROOT has dictionary for all its types

# Back To Saving Objects



Given a TFile:

```
TFile* f = TFile::Open("file.root", "RECREATE");
```

Write an object deriving from TObject:

```
object->Write("optionalName")
```

"optionalName" or TObject::GetName()

Write any object (with dictionary):

```
f->WriteObject(object, "name");
```

# TFile



ROOT stores objects in TFiles:

```
TFile* f = TFile::Open("file.root", "NEW");
```

TFile behaves like file system:

```
f->mkdir("dir");
```

TFile has a current directory:

```
f->cd("dir");
```

TFile compresses data ("zip"):

```
f->GetCompressionFactor()
2.6
```

# "Where Is My Histogram?"

TFile owns histograms, graphs, trees  
(due to historical reasons):

```
TFile* f = TFile::Open("myfile.root");
TH1F* h = new TH1F("h","h",10,0.,1.);
TNamed* o = new TNamed("name", "title");
o->Write();
delete f;
```

h automatically deleted: owned by file.

o still there

even if saving o to file!

*unique names!*

TFile acts like a scope for hists, graphs, trees!

# Risks With I/O



Physicists can loop a lot:

*For each particle collision*

*For each particle created*

*For each detector module*

*Do something.*

Physicists can loose a lot:

*Run for hours...*

*Crash.*

*Everything lost.*

# Name Cycles

Create snapshots regularly:

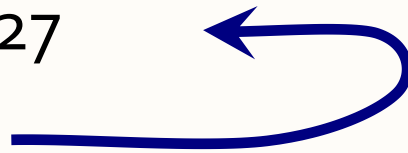
MyObject;1

MyObject;2

...

MyObject;5427

MyObject



Write() does not replace but append!  
but see documentation TObject::Write()

# The "I" Of I/O



Reading is simple:

```
TFile* f = TFile::Open("myfile.root");
TH1F* h = 0;
f->GetObject("h", h);
h->Draw();
delete f;
```

Remember:

TFile owns histograms!  
file gone, histogram gone!

# Ownership And TFiles



Separate TFile and histograms:

```
TFile* f = TFile::Open("myfile.root");
TH1F* h = 0;
TH1::AddDirectory(kFALSE);
f->GetObject("h", h);
h->Draw();
delete f;
```

... and h will stay around.

Put in root\_logon.C in current directory to be executed  
when root starts



# Changing Class – The Problem



Things change:

```
class TMyClass {
 float fFloat;
 Long64_t fLong;
};
```

# Changing Class – The Problem



Things change:

```
class TMyClass {
 double fFloat;
 Long64_t fLong;
};
```

Inconsistent reflection data, mismatch in memory, on disk

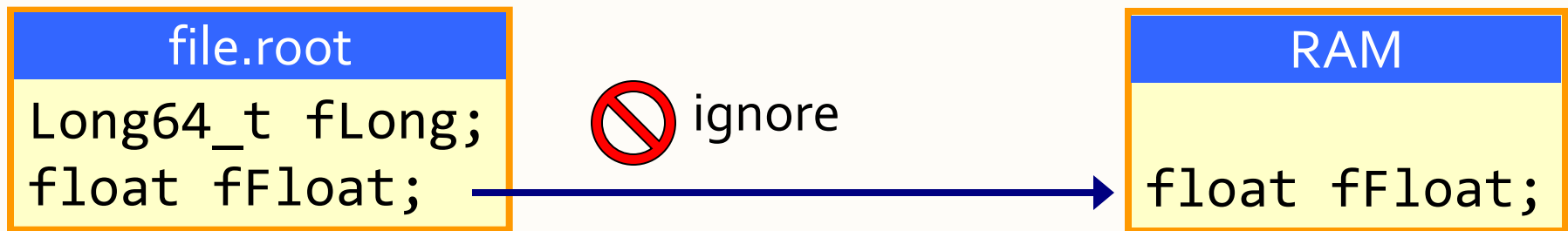
Objects written with old version cannot be read

*Need to store reflection with data to detect!*

# Schema Evolution

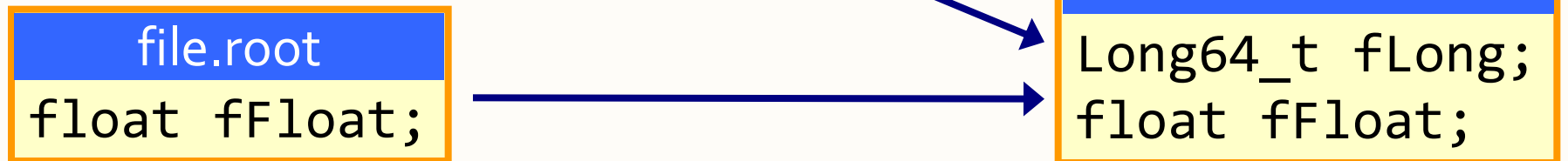
Simple rules to convert disk to memory layout

1. skip removed members



2. default-initialize added members

TMyClass(): fLong(0)



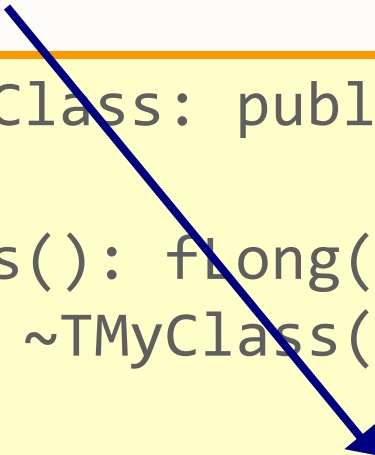
3. convert members where possible

# Class Version

ClassDef() macro makes I/O faster, needed when deriving from TObject

Can have multiple class versions in same file

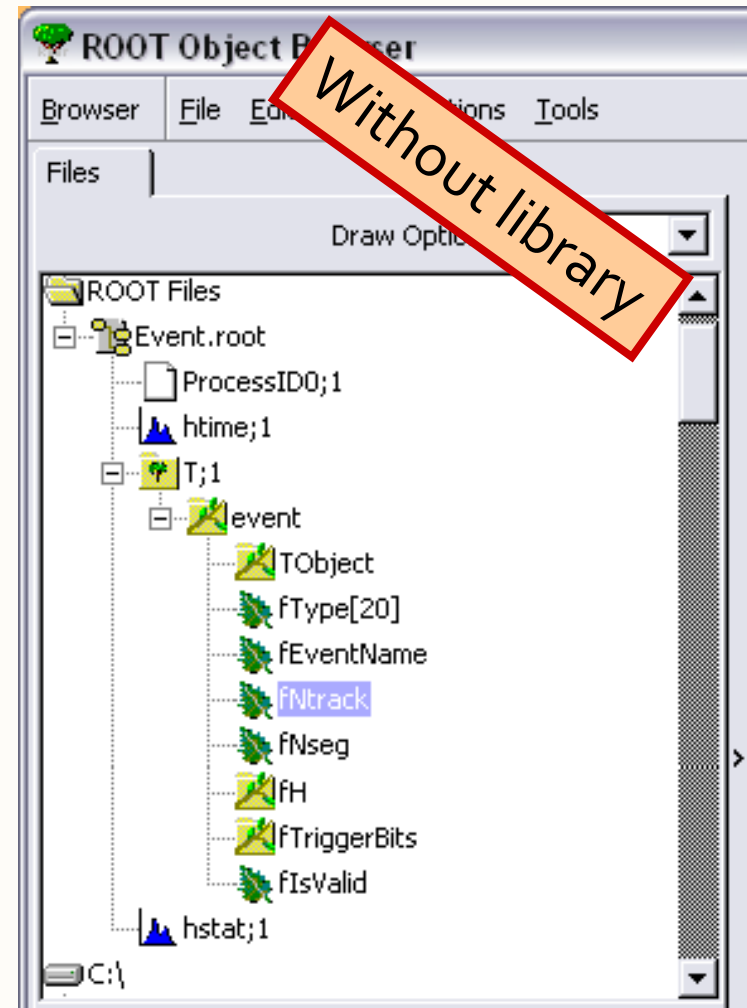
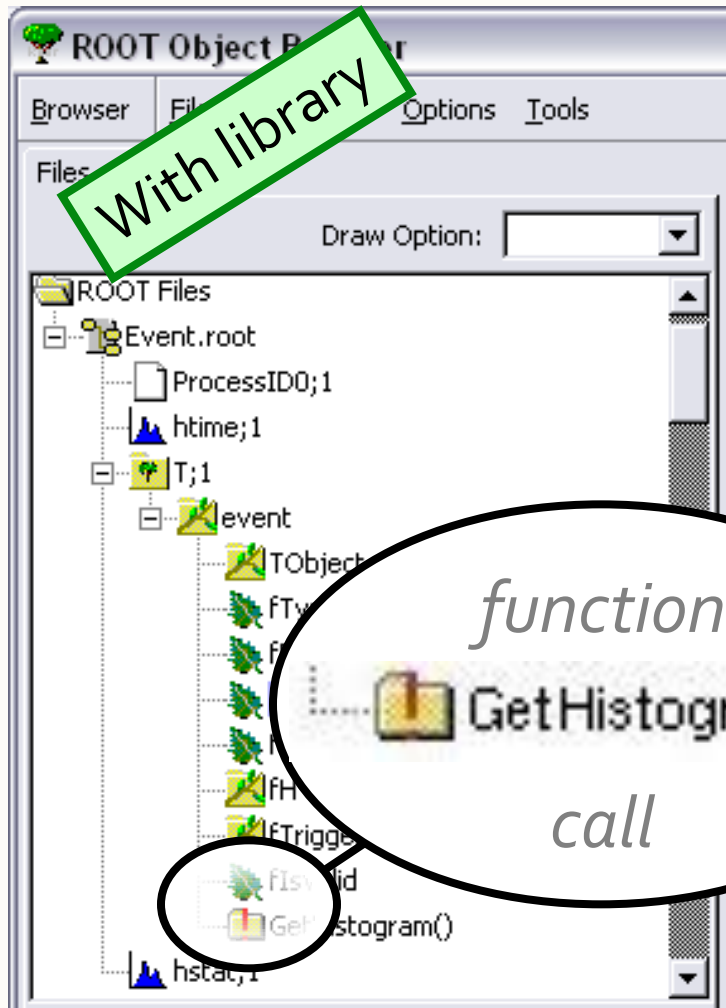
Use version number to identify layout:



```
class TMyClass: public TObject {
public:
 TMyClass(): fLong(0), fFloat(0.) {}
 virtual ~TMyClass() {}
 ...
 ClassDef(TMyClass,1); // example class
};
```

# Reading Files

Files store reflection and data: need no library!



# ROOT I/O Candy



- Nice viewer for TFile: new TBrowser
- Can even open  
TFile::Open("<http://cern.ch/file.root>") including  
read-what-you-need!
- Combine contents of TFiles with \$ROOTSYS/bin/hadd

# Summary



Big picture:

- you know ROOT files – for petabytes of data
- you learned that reflection is key for I/O
- you learned what schema evolution is

Small picture:

- you can write your own data to files
- you can read it back
- you can change the definition of your classes



# ROOT COLLECTION CLASSES



# Collection Classes



ROOT collections polymorphic containers: hold pointers to TObject, so:

- Can only hold objects that inherit from TObject
- Return pointers to TObject, that have to be cast back to the correct subclass

```
void DrawHist(TObjArray *vect, int at)
{
 TH1F *hist = (TH1F*)vect->At(at);
 if (hist) hist->Draw();
}
```

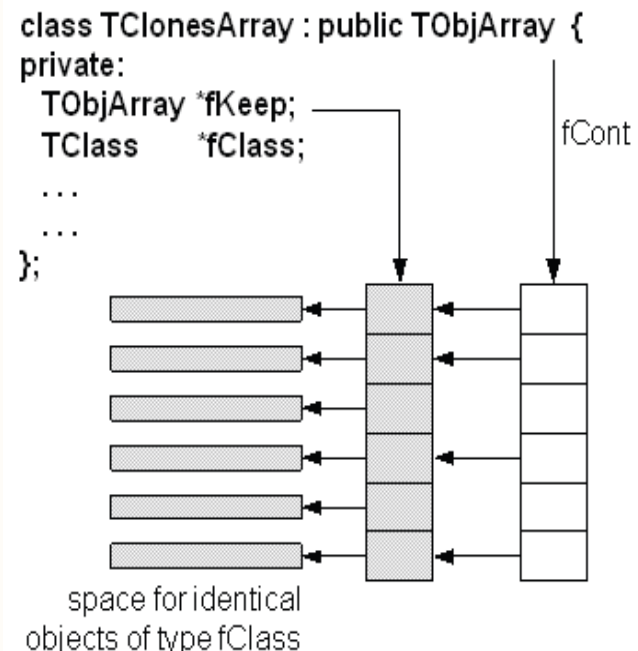
# TClonesArray

Array of objects of the same class ("clones")

Designed for repetitive data analysis tasks:

same type of objects  
created and deleted  
many times.

No comparable class in STL!

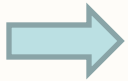


*The internal data structure of a  
TClonesArray*

# TClonesArray

Standard array:

```
while (next_event()) {
 for (int i=0;i<N;++i)
 a[i] = new TTrack(x,y,z);
 do_something(a);
 a.clear();
};
```



TClonesArray:

```
while (next_event()) {
 for (int i=0;i<N;++i)
 new(a[i]) TTrack(x,y,z);
 do_something(a);
 a.Delete();
};
```



# Traditional Arrays

Very large number of new and delete calls in large loops like this ( $N_{\text{events}} \times N_{\text{tracks}}$  times new/delete):

```
TObjArray a(10000);
while (TEvent *ev = (TEvent *)next()) {
 for (int i = 0; i < ev->Ntracks; ++i) {
 a[i] = new TTrack(x,y,z,...);
 ...
 }
 a.Delete();
}
```

$N_{\text{events}}$   
= 100000

$N_{\text{tracks}}$   
= 10000

# Use of TClonesArray

You better use a TClonesArray which reduces the number of new/delete calls to only  $N_{\text{tracks}}$ :

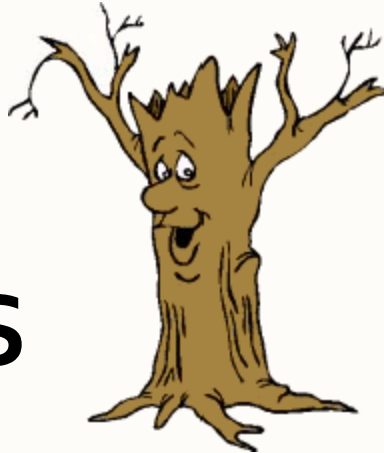
```
TClonesArray a("TTrack", 10000);
while (TEvent *ev = (TEvent *)next()) {
 for (int i = 0; i < ev->Ntracks; ++i) {
 new(a[i]) TTrack(x,y,z,...);
 ...
 }
 a.Delete();
}
```

$N_{\text{events}}$   
= 100000

$N_{\text{tracks}}$   
= 10000

- Pair of new / delete calls cost about  $4 \mu\text{s}$
- Allocating / freeing memory  $N_{\text{events}} * N_{\text{tracks}} = 10^9$  times costs about 1 hour!

# ROOT TREES

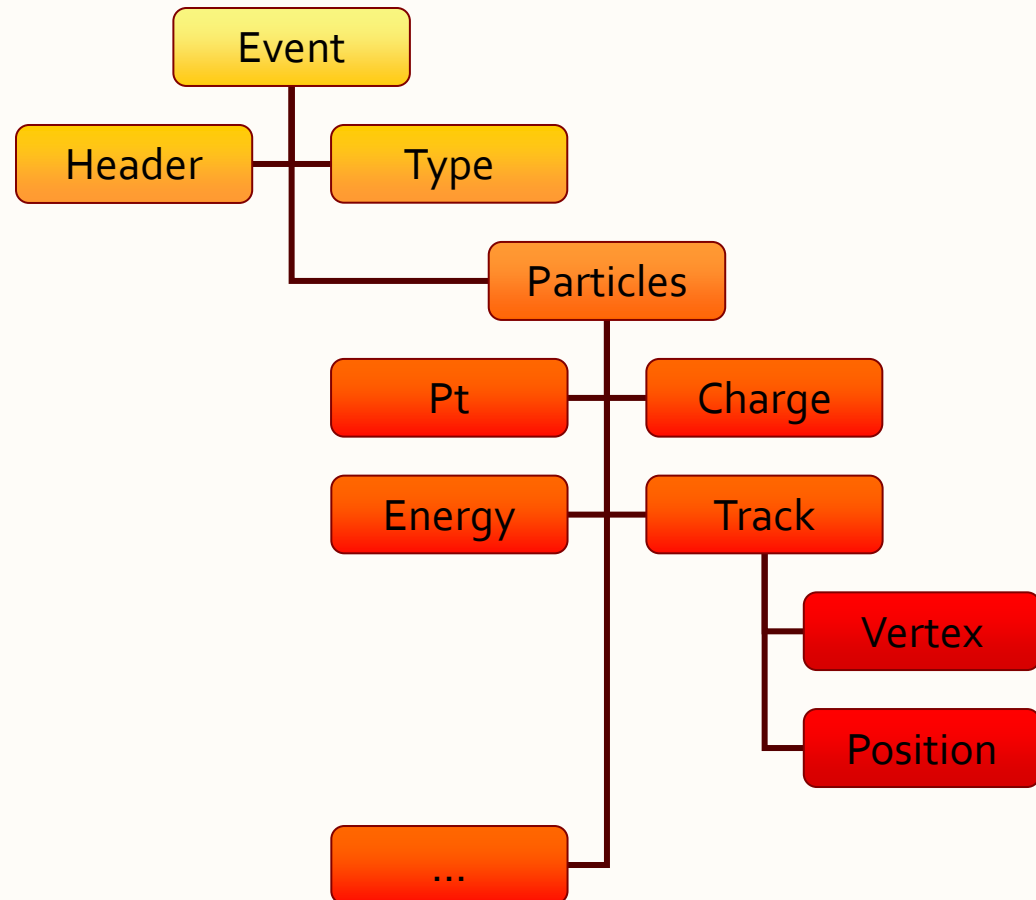


# Trees

From:  
Simple data types  
(e.g. Excel tables)

| x        | y        | z        |
|----------|----------|----------|
| -1.10228 | -1.79939 | 4.452822 |
| 1.867178 | -0.59662 | 3.842313 |
| -0.52418 | 1.868521 | 3.766139 |
| -0.38061 | 0.969128 | 1.084074 |
| 0.552454 | -0.21231 | 0.350281 |
| -0.18495 | 1.187305 | 1.443902 |
| 0.205643 | -0.77015 | 0.635417 |
| 1.079222 | -0.32739 | 1.271904 |
| -0.27492 | -1.72143 | 3.038899 |
| 2.047779 | -0.06268 | 4.197329 |
| -0.45868 | -1.44322 | 2.293266 |
| 0.304731 | -0.88464 | 0.875442 |
| -0.71234 | -0.22239 | 0.556881 |
| -0.27187 | 1.181767 | 1.470484 |
| 0.886202 | -0.65411 | 1.213209 |
| -2.03555 | 0.527648 | 4.421883 |
| -1.45905 | -0.464   | 2.344113 |
| 1.230661 | -0.00565 | 1.514559 |
|          |          | 3.562347 |

To:  
Complex data types  
(e.g. Database tables)



# Why Trees ?



- Extremely efficient write once, read many ("WORM")
- Designed to store  $>10^9$  (HEP events) with same data structure
- Trees allow fast direct and random access to any entry (sequential access is the best)
- Optimized for network access (read-ahead)





# Why Trees ?



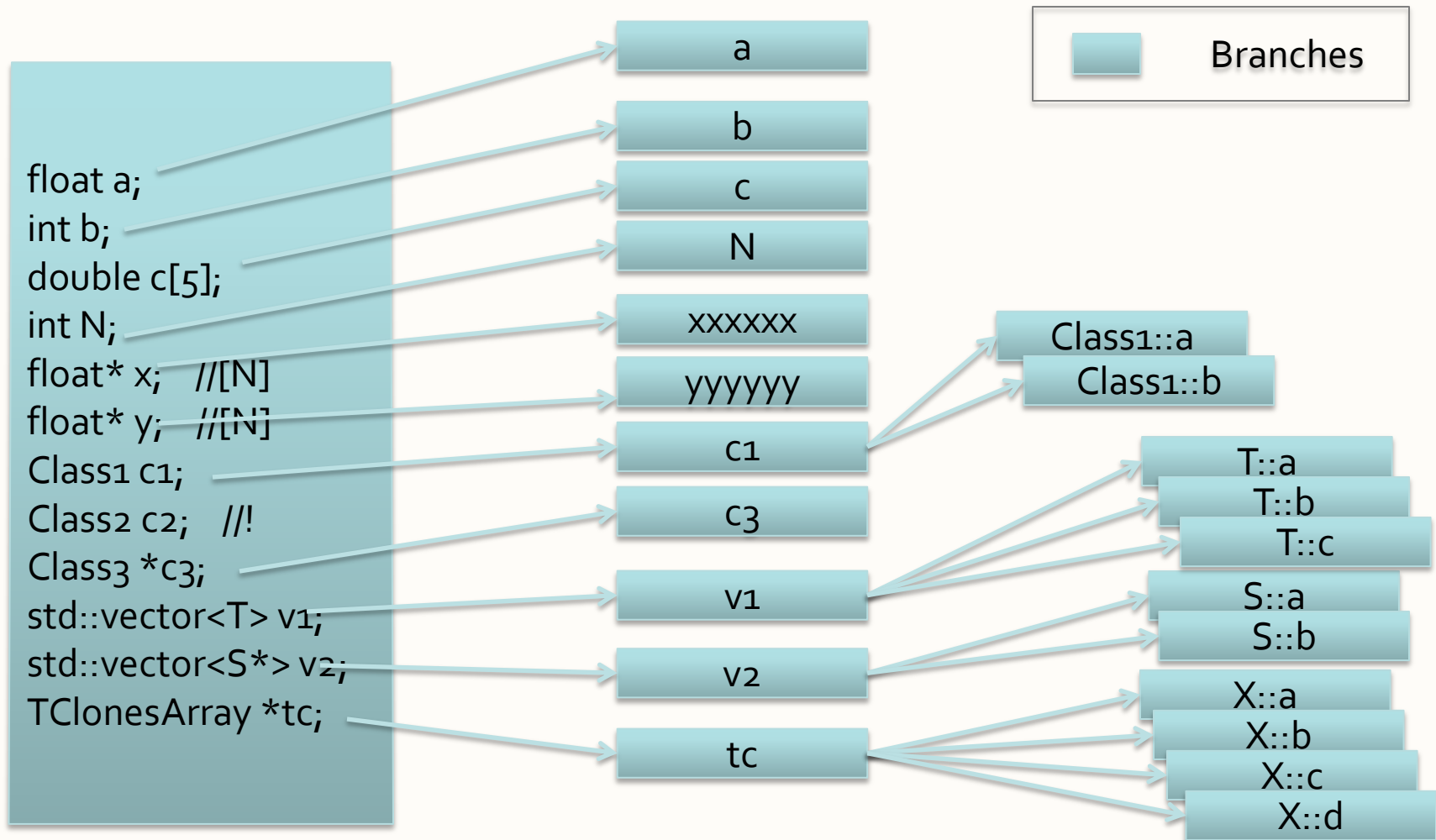
- object.Write() convenient for simple objects like histograms, inappropriate for saving collections of events containing complex objects
- Reading a collection: read all elements (all events)
  - With trees: only one element in memory, or even only a part of it (less I/O)
  - Trees buffered to disk (TFile); I/O is integral part of TTree concept

# Tree Access



- Databases have row wise access
  - Can only access the full object (e.g. full event)
- ROOT trees have column wise access
  - Direct access to any event, any branch or any leaf even in the case of variable length structures
  - Designed to access only a subset of the object attributes (e.g. only particles' energy)
  - Makes same members consecutive, e.g. for object with position in X, Y, Z, and energy E, all X are consecutive, then come Y, then Z, then E. A lot higher zip efficiency!

# Branch Creation from Class

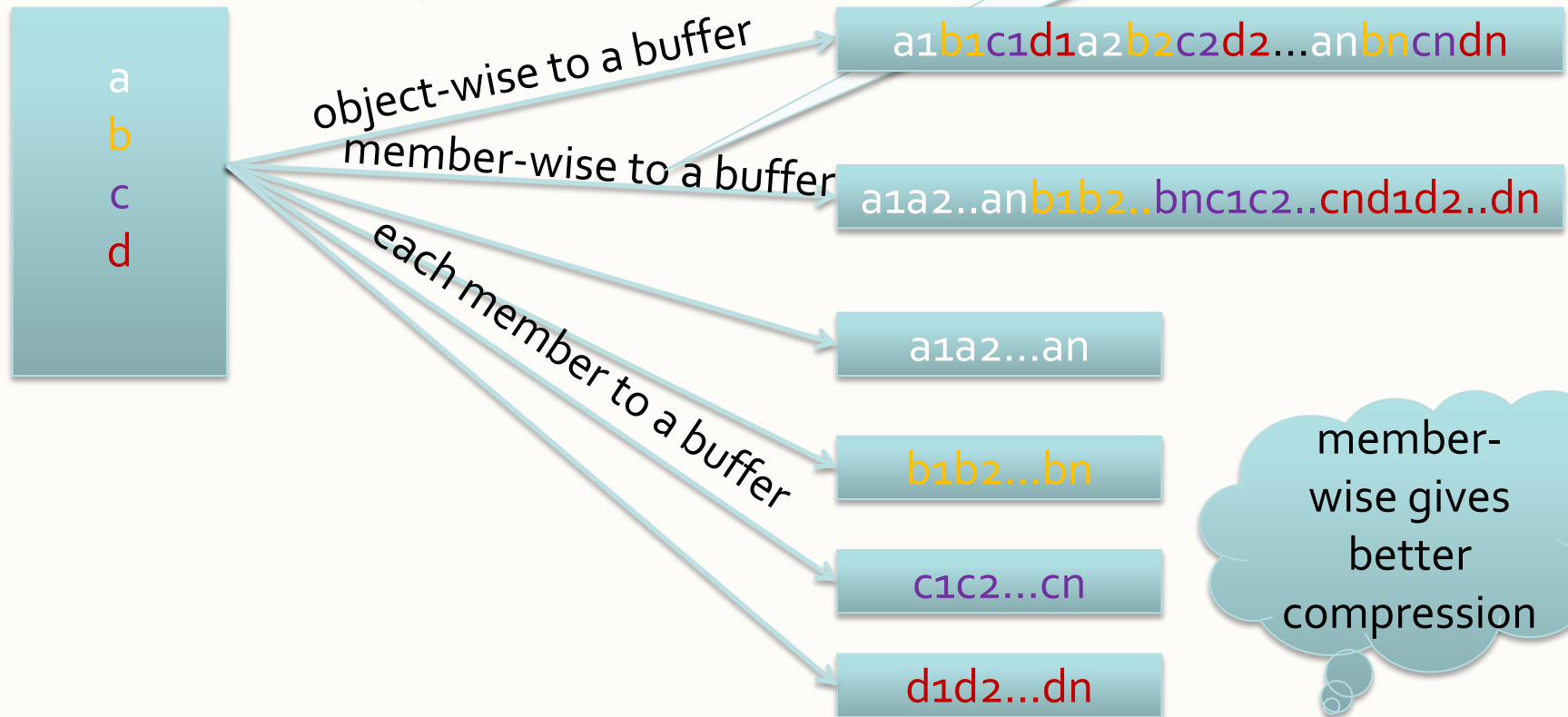


# ObjectWise/MemberWise Streaming



3 modes to stream  
an object

member-wise  
streaming of  
collections default  
since 5.27



# Building ROOT Trees



## Overview of

- Trees
- Branches

5 steps to build a TTree

# Tree structure



**ROOT Browser**

File View Options

fTracks

All Folders

- root
- PROOF Sessions
- C:\home\belleno\root\tutorials\tree
- ROOT Files
  - tree4.root
    - t4
      - event\_split
        - TObject
        - fEvtHdr
        - fTracks
        - fH
        - fTriggerBits
        - GetHistogram()

Contents of "/ROOT Files/tree4.root/t4/event\_split/fTracks"

| Name                | Title                 |
|---------------------|-----------------------|
| fTracks.fBits       | fBits[fTracks_]       |
| fTracks.fBx         | fBx[fTracks_]         |
| fTracks.fBy         | fBy[fTracks_]         |
| fTracks.fCharge     | fCharge[fTracks_]     |
| fTracks.fMass2      | fMass2[fTracks_]      |
| fTracks.fMeanCharge | fMeanCharge[fTracks_] |
| fTracks.fNpoint     | fNpoint[fTracks_]     |
| fTracks.fNsp        | fNsp[fTracks_]        |
| fTracks.fPointValue | fPointValue[fTracks_] |
| fTracks.fPx         | fPx[fTracks_]         |
| fTracks.fPy         | fPy[fTracks_]         |
| fTracks.fPt         | fPt[fTracks_]         |

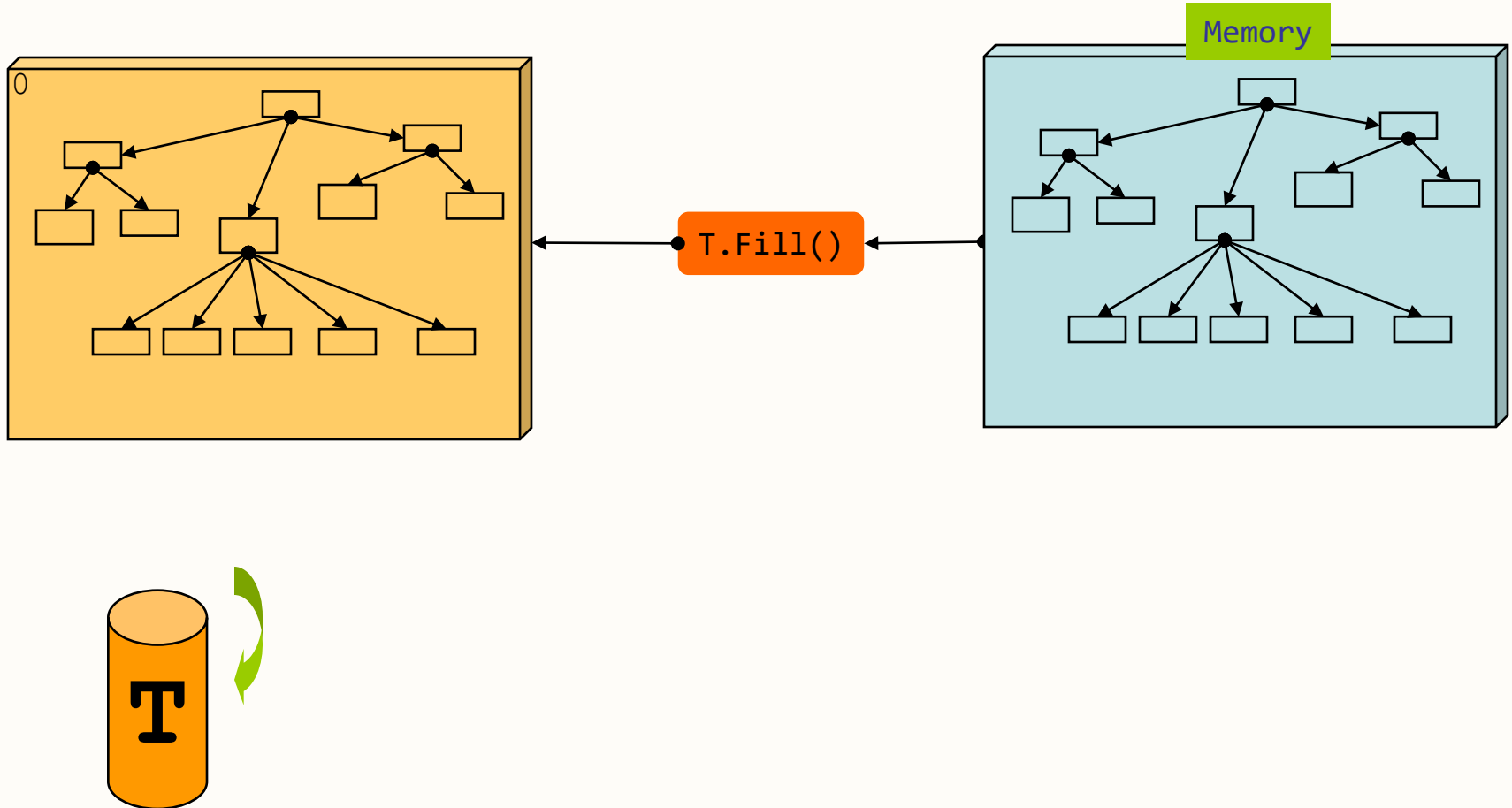
# Tree structure



- Branches: directories
- Leaves: data containers
- Can read a subset of all branches – speeds up considerably the data analysis processes
- Branches of the same **TTree** can be written to separate files

# Memory $\leftrightarrow$ Tree

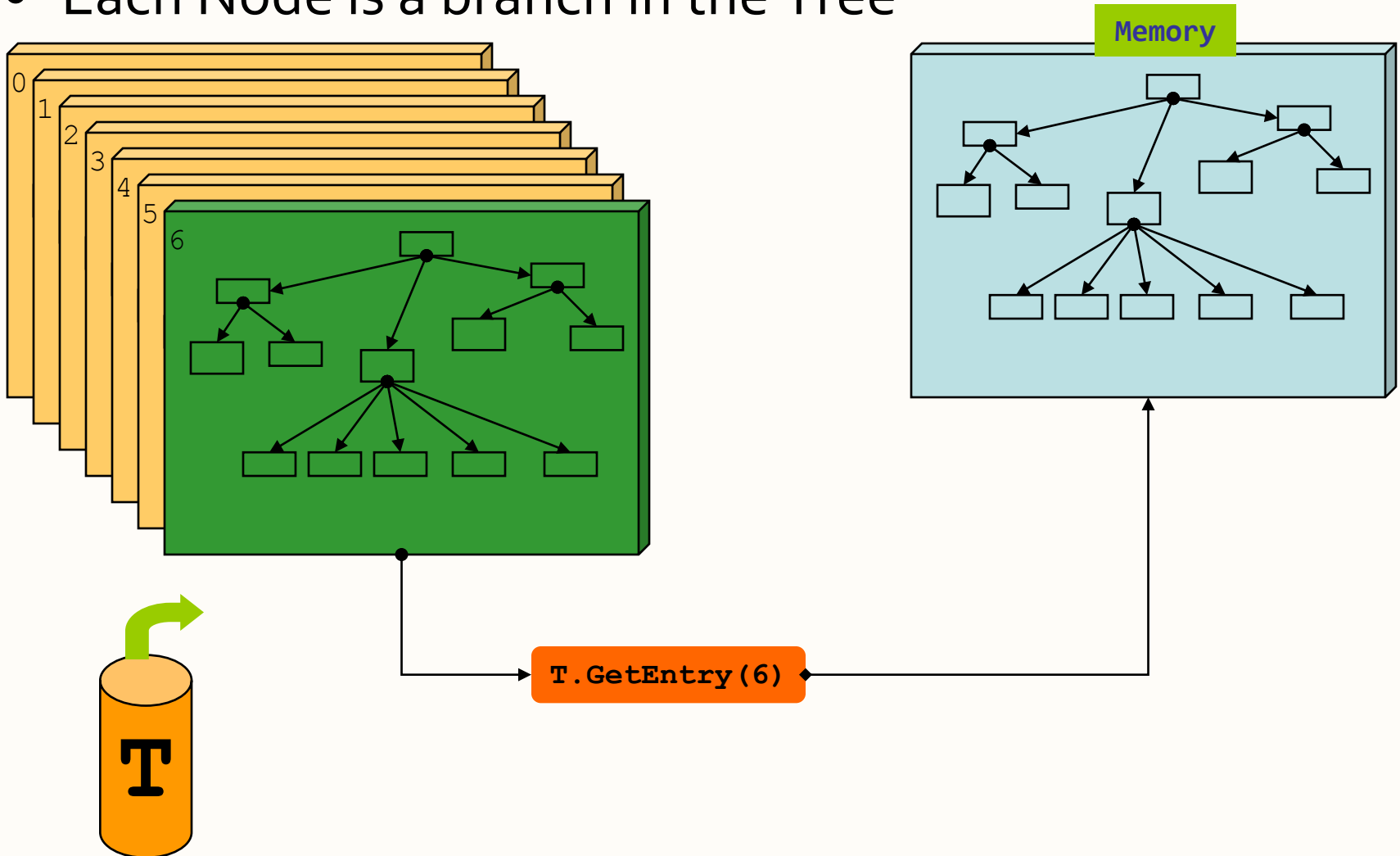
- Each Node is a branch in the Tree





# Memory $\leftrightarrow$ Tree

- Each Node is a branch in the Tree



# Five Steps to Build a Tree



## Steps:

1. Create a TFile
2. Create a TTree
3. Add TBranch to the TTree
4. Fill the tree
5. Write the file

# Example macro

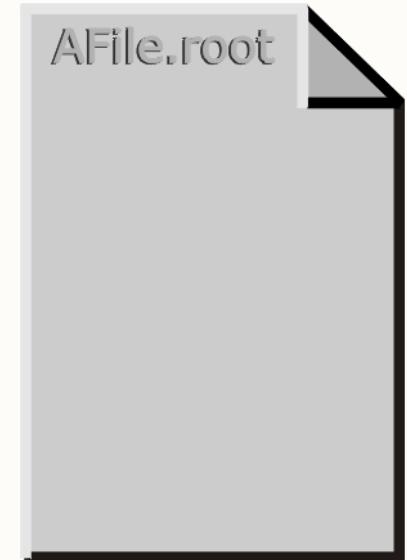


```
void WriteTree()
{
 Event *myEvent = new Event();
 TFile f("AFile.root", "RECREATE");
 TTree *t = new TTree("myTree","A Tree");
 t->Branch("EventBranch", &myEvent);
 for (int e=0;e<100000;++e) {
 myEvent->Generate(); // hypothetical
 t->Fill();
 }
 t->Write();
}
```

# Step 1: Create a TFile Object



Trees can be huge → need file for swapping filled entries



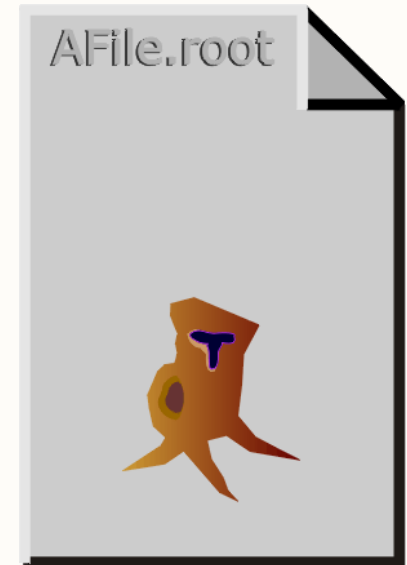
```
TFile *hfile = TFile::Open("AFile.root",
 "RECREATE");
```

# Step 2: Create a TTree Object



The TTree constructor:

- Tree name (e.g. "myTree")
- Tree title

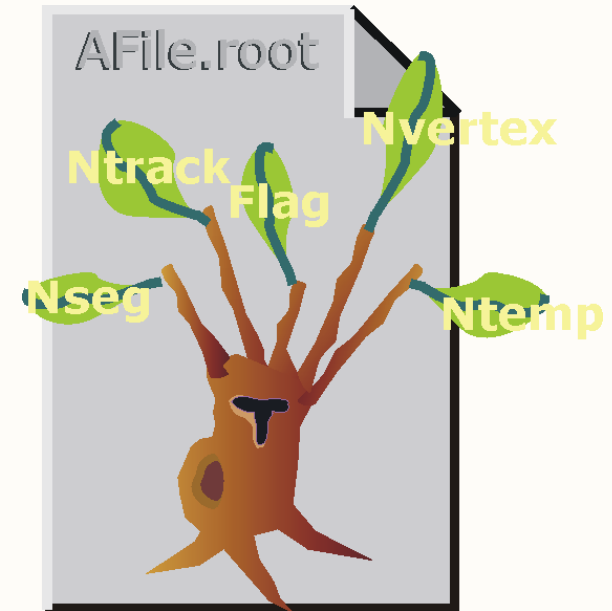


```
TTree *tree = new TTree("myTree", "A Tree");
```

# Step 3: Adding a Branch



- Branch name
- Address of pointer  
to the object

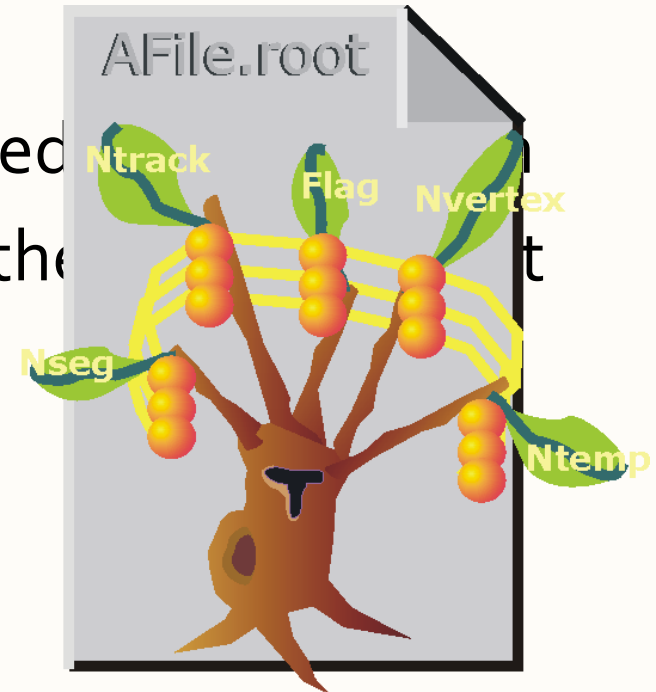


```
Event *myEvent = new Event();
myTree->Branch("eBranch", &myEvent);
```

# Step 4: Fill the Tree



- Create a for loop
- Assign values to the object contained
- TTree::Fill() creates a new entry in the tree of values of branches' objects

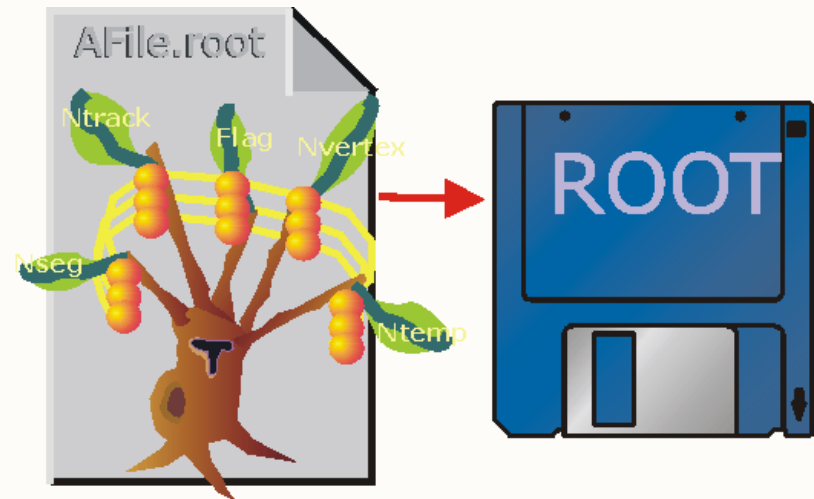


```
for (int e=0;e<100000;++e) {
 myEvent->Generate(e); // fill event
 myTree->Fill(); // fill the tree
}
```

# Step 5: Write Tree To File



```
myTree->Write();
```





# Reading a TTree



- Looking at a tree
- How to read a tree
- Friends and chains

# Example macro



```
void ReadTree() {
 TFile f("AFile.root");
 TTree *T = (TTree*)f->Get("T");
 Event *myE = 0; TBranch* brE = 0;
 T->SetBranchAddress("EvBranch", &myE, brE);
 T->SetCacheSize(10000000);
 T->AddBranchToCache("EvBranch");
 Long64_t nbent = T->GetEntries();
 for (Long64_t e = 0; e < nbent; ++e) {
 brE->GetEntry(e);
 myE->Analyze();
 }
}
```



Data pointers (e.g. myE) MUST be set to 0

# How to Read a TTree



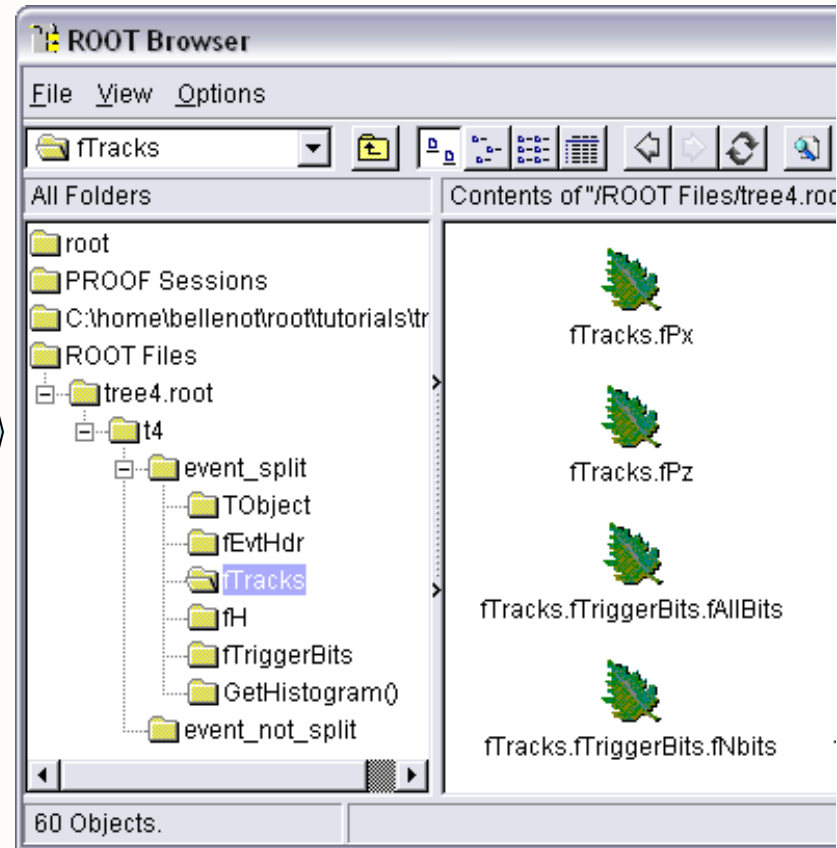
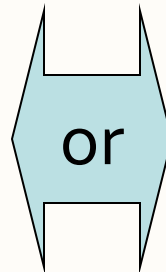
Example:

1. Open the Tfile

```
TFile f("AFile.root")
```

2. Get the TTree

```
TTree *myTree = 0;
f.GetObject("myTree", my
Tree)
```



# How to Read a TTree



3. Create a variable pointing to the data

```
root [] Event *myEvent = 0;
```

4. Associate a branch with the variable:

```
root [] myTree->SetBranchAddr("eBranch", &myEvent);
```

5. Read one entry in the TTree

```
root [] myTree->GetEntry(0)
```

```
root [] myEvent->GetTracks()->First()->Dump()
```

```
==> Dumping object at: 0x0763aad0, name=Track, class=Track
```

```
fPx 0.651241 X component of the momentum
```

```
fPy 1.02466 Y component of the momentum
```

```
fPz 1.2141 Z component of the momentum
```

```
[...]
```

# Branch Access Selection



- Use `TTree::SetBranchStatus()` or `TBranch::GetEntry()` to select branches to be read
- Speed up considerably the reading phase

```
TClonesArray* myMuons = 0;
// disable all branches
myTree->SetBranchStatus("*", 0);
// re-enable the "muon" branches
myTree->SetBranchStatus("muon*", 1);
myTree->SetBranchAddress("muon", &myMuons);
// now read (access) only the "muon" branches
myTree->GetEntry(0);
```

# Looking at the Tree



TTree::Print() shows the data layout

```
root [] TFile f("AFile.root")
root [] myTree->Print();
```

```

*Tree :myTree : A ROOT tree *
*Entries : 10 : Total = 867935 bytes File Size = 390138 *
* : : Tree compression factor = 2.72 *

*Branch :eBranch *
*Entries : 10 : BranchElement (see below) *
.....
*Br 0 :fUniqueID : *
*Entries : 10 : Total Size= 698 bytes One basket in memory *
*Baskets : 0 : Basket Size= 64000 bytes Compression= 1.00 *
.....
...
...
```

# Looking at the Tree

TTree::Scan("leaf:leaf:....") shows the values

```
root [] myTree->Scan("fNseg:fNtrack"); > scan.txt
```

```
root [] myTree->Scan("fEvtHdr.fDate:fNtrack:fPx:fPy","",
 "colsize=13 precision=3 col=13:7::15.10");
```

```

* Row * Instance * fEvtHdr.fDate * fNtrack * fPx * fPy *

* 0 * 0 * 960312 * 594 * 2.07 * 1.459911346 *
* 0 * 1 * 960312 * 594 * 0.903 * -0.4093382061 *
* 0 * 2 * 960312 * 594 * 0.696 * 0.3913401663 *
* 0 * 3 * 960312 * 594 * -0.638 * 1.244356871 *
* 0 * 4 * 960312 * 594 * -0.556 * -0.7361358404 *
* 0 * 5 * 960312 * 594 * -1.57 * -0.3049036264 *
* 0 * 6 * 960312 * 594 * 0.0425 * -1.006743073 *
* 0 * 7 * 960312 * 594 * -0.6 * -1.895804524 *
```

# TTree Selection Syntax

Print the first 8 variables of the tree:

```
MyTree->Scan();
```

Prints all the variables of the tree:

```
MyTree->Scan("*");
```

Prints the values of var1, var2 and var3.

```
MyTree->Scan("var1:var2:var3");
```

A selection can be applied in the second argument:

```
MyTree->Scan("var1:var2:var3", "var1>0");
```

Prints the values of var1, var2 and var3 for the entries where var1 is greater than 0

Use the same syntax for TTree::Draw()



# Looking at the Tree



TTree::Show(entry\_number) shows values for one entry

```
root [] myTree->Show(0);
```

```
=====> EVENT:0
```

```
eBranch = NULL
```

```
fUniqueID = 0
```

```
fBits = 50331648
```

```
[...]
```

```
fNtrack = 594
```

```
fNseg = 5964
```

```
[...]
```

```
fEvtHdr.fRun = 200
```

```
[...]
```

```
fTracks.fPx = 2.066806, 0.903484, 0.695610, -0.637773,...
```

```
fTracks.fPy = 1.459911, -0.409338, 0.391340, 1.244357,...
```

# TChain: the Forest



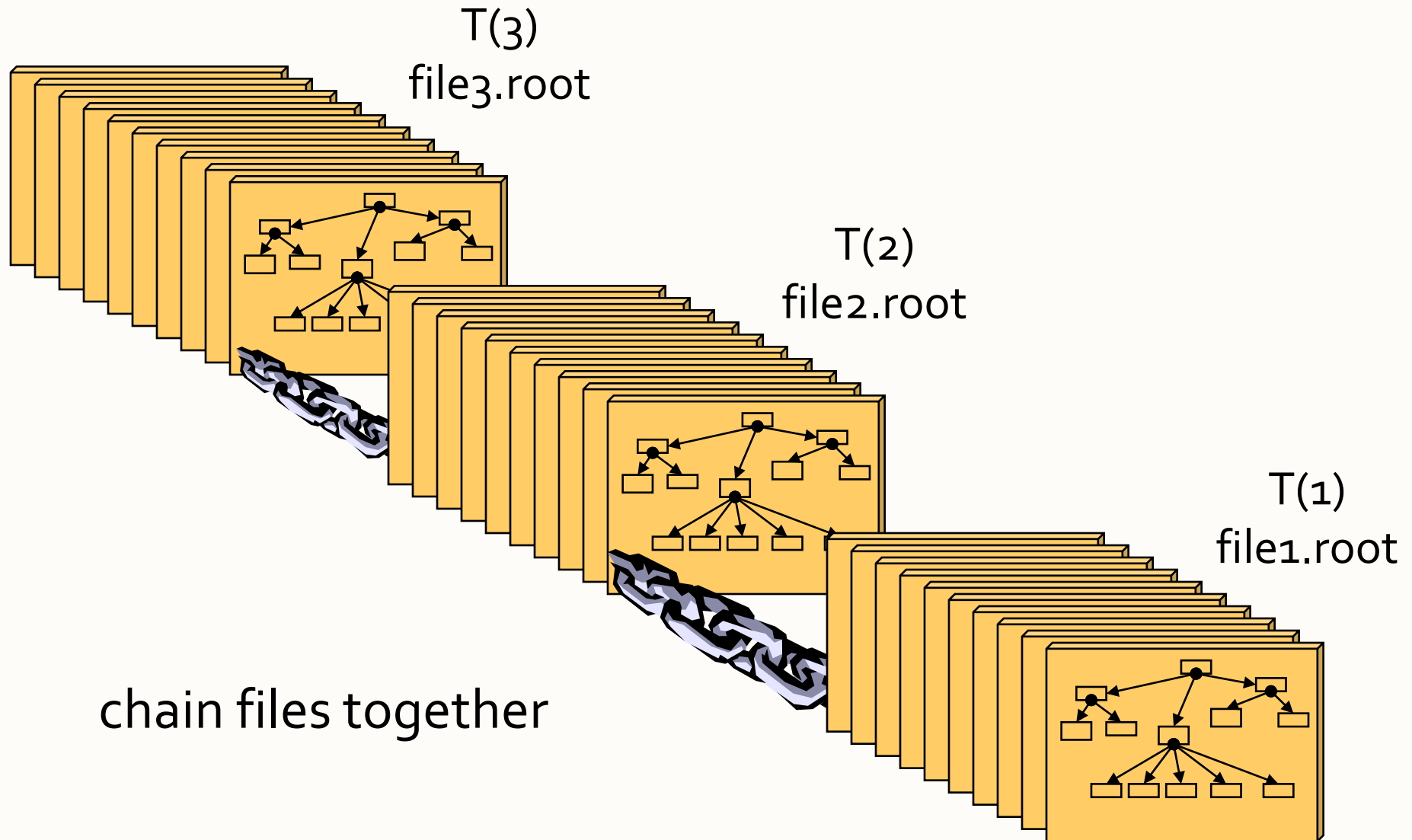
- Collection of TTrees: list of ROOT files containing the same tree
- Same semantics as TTree

As an example, assume we have three files called file1.root, file2.root, file3.root. Each contains tree called "T". Create a chain:

```
TChain chain("T"); // argument: tree name
chain.Add("file1.root");
chain.Add("file2.root");
chain.Add("file3.root");
```

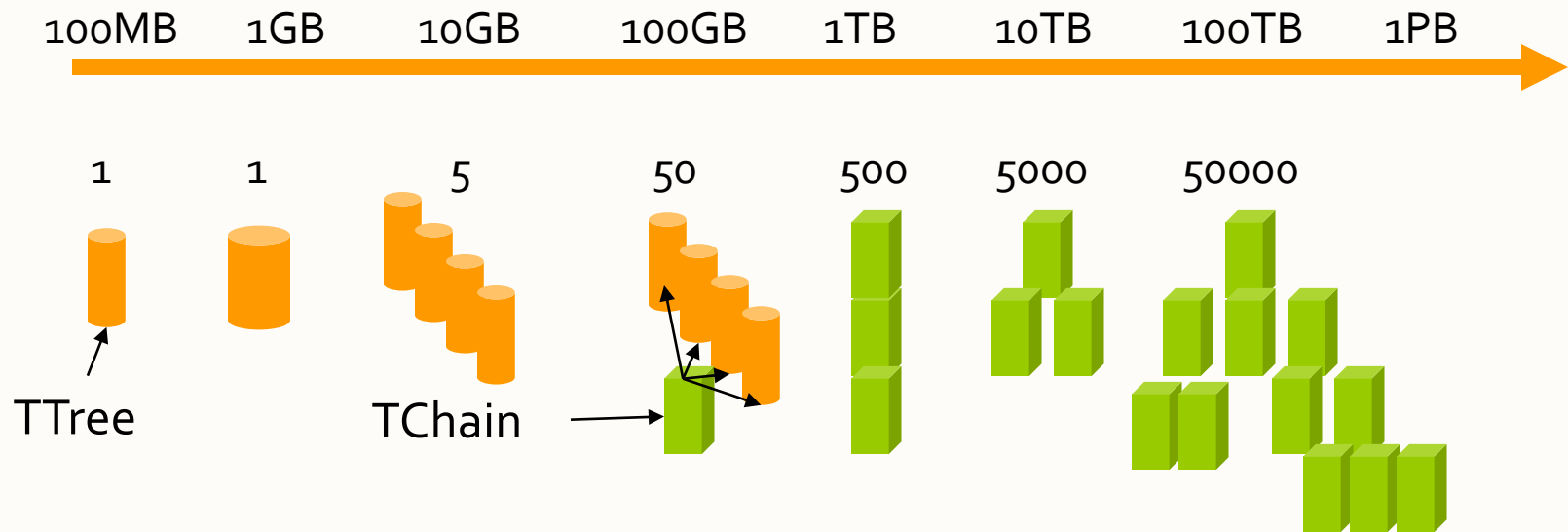
Now we can use the TChain like a TTree!

# TChain



# Data Volume & Organisation

- A TFile typically contains 1 TTree
- A TChain is a collection of TTrees or/and TChains

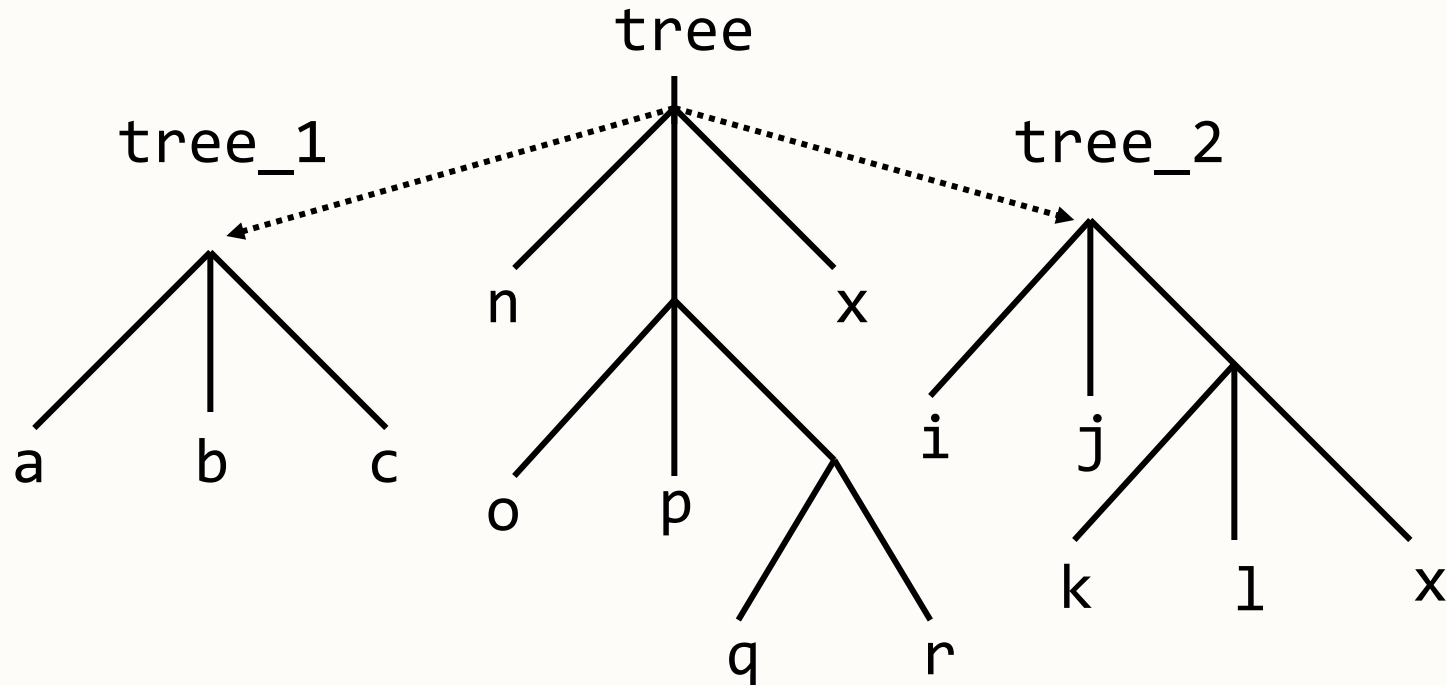


# Tree Friends



- Trees are designed to be read only
- Often, people want to add branches to existing trees and write their data into it
- Using tree friends is the solution:
  - Create a new file holding the new tree
  - Create a new Tree holding the branches for the user data
  - Fill the tree/branches with user data
  - Add this new file/tree as friend of the original tree

# Tree Friends

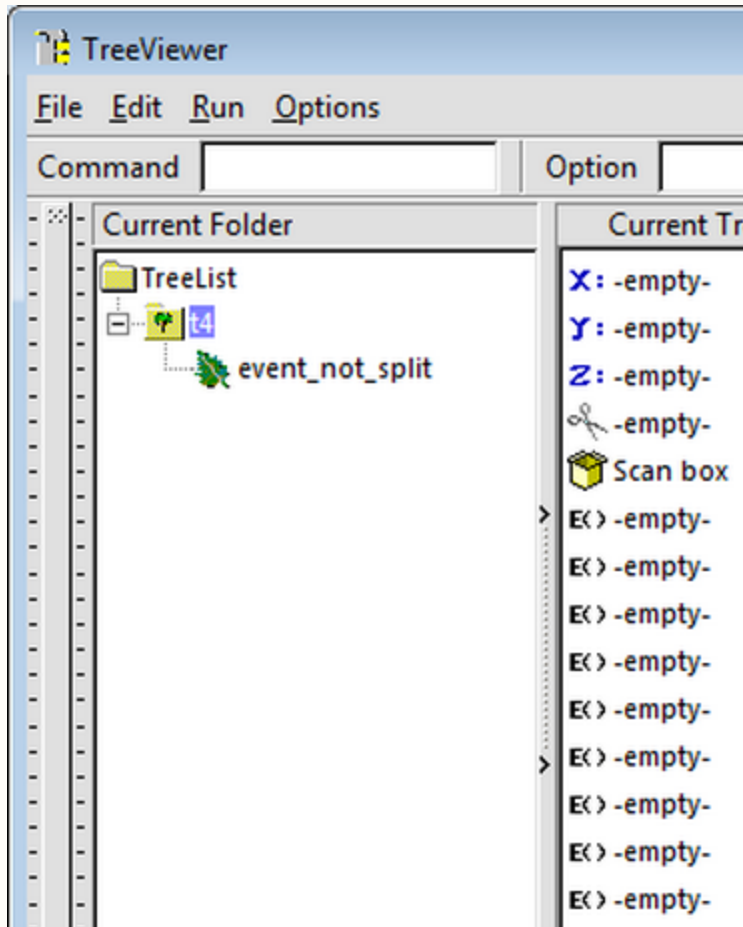


```

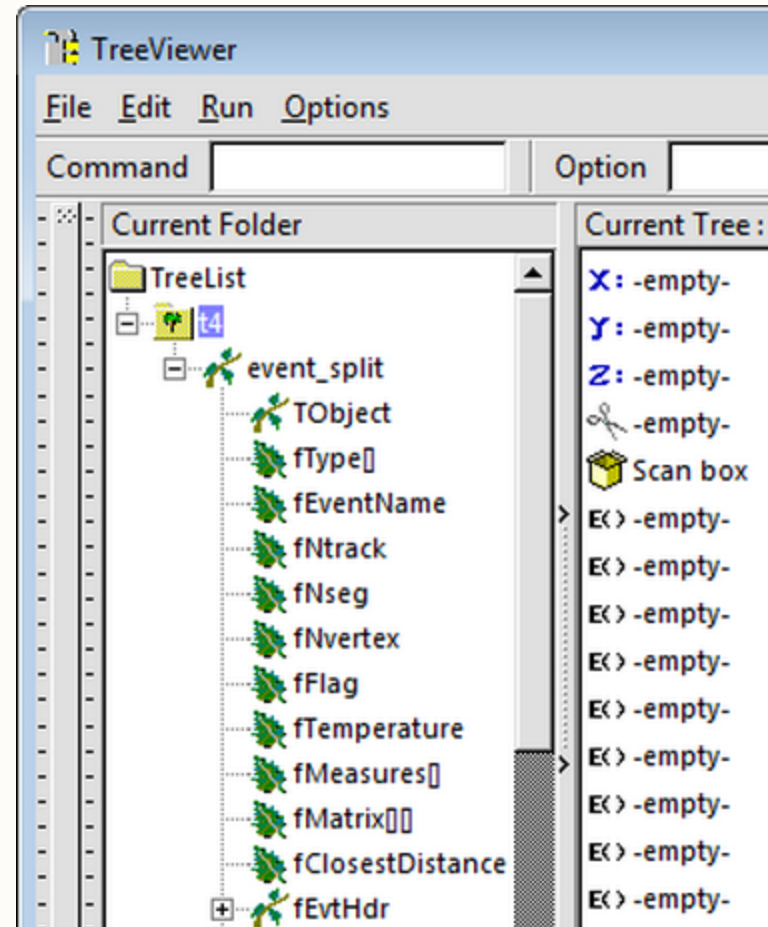
TFile f1("tree.root");
tree.AddFriend("tree_1", "tree1.root");
tree.AddFriend("tree_2", "tree2.root");
tree.Draw("x:a", "k<c");
tree.Draw("x:tree_2.x");

```

# Splitting



Split level = 0



Split level = 99

# Splitting



- Creates one branch per member – recursively
- Allows to browse objects that are stored in trees, even without their library
- Fine grained branches allow fine-grained I/O - read only members that are needed
- Supports STL containers too, even `vector<T*>!`

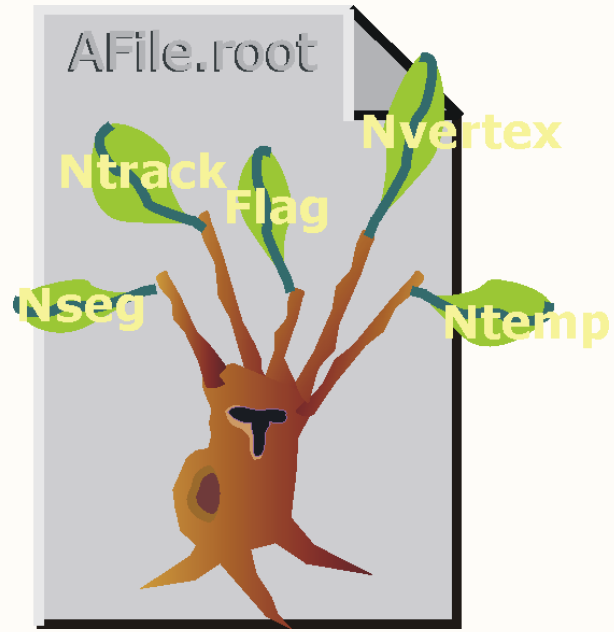


# Splitting

Setting the split level (default = 99)



Split level = 0



Split level = 99

```
tree->Branch("EvBr", &event, 64000, 0);
```

# Performance Considerations

A split branch is:

- Faster to read – if you only want a subset of data members
- Slower to write due to the large number of branches

# Summary: Trees



- TTree is one of the most powerful collections available for HEP
- Extremely efficient for huge number of data sets with identical layout
- Very easy to look at TTree - use TBrowser!
- Write once, read many (WORM) ideal for experiments' data; use friends to extend
- Branches allow granular access; use splitting to create branch for each member, even through collections

The background of the slide features a large, leafy tree with a bright sunburst effect behind its trunk. A magnifying glass is positioned on the right side of the tree, focusing on a small branch. The overall image is semi-transparent, allowing the text to be clearly visible.

Selectors, Analysis, PROOF

# ANALYZING TREES

# Recap

TTree efficient storage and access  
for huge amounts of structured data

Allows selective access of data

TTree knows its layout

Almost all HEP analyses based on TTree

# TTree Data Access



TSelector: generic "TTree based analysis"

Derive from it ("TMySelector")

ROOT invokes TSelector's functions,

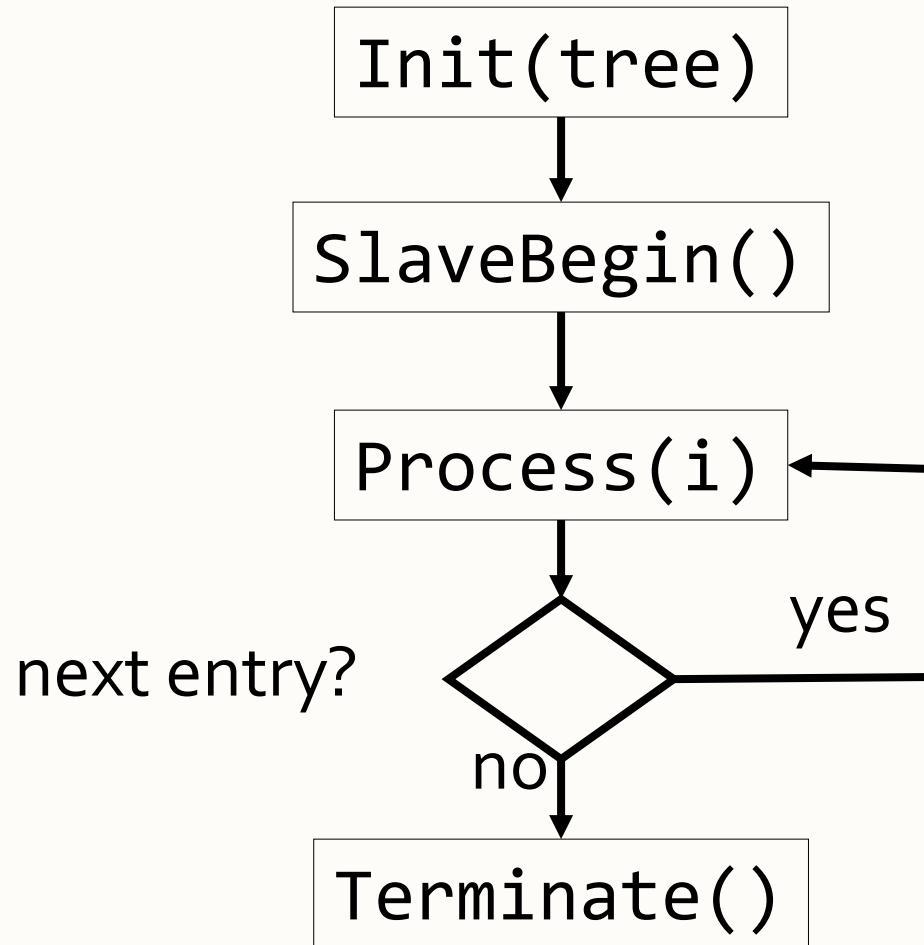
Used e.g. by tree->**Process**(TSelector\*,...), PROOF

Functions called are virtual, thus TMySelector's functions called.

# TTree Data Access

E.g.

```
tree->Process("MySelector.C+")
```



# TSelector



Steps of ROOT using a TSelector:

- 1. *setup*** TMySelector::Init(TTree \*tree)  
fChain = tree; fChain->SetBranchAddresses()
- 2. *start*** TMySelector::SlaveBegin()  
create histograms
- 3. *run*** TMySelector::Process(Long64\_t)  
fChain->GetTree()->GetEntry(entry);  
analyze data, fill histograms,...
- 4. *end*** TMySelector::Terminate()  
fit histograms, write them to files,...



# Analysis



TSelector gives the structure of analyses

Content of data analysis:

science by itself

covered by Ivica Puljak

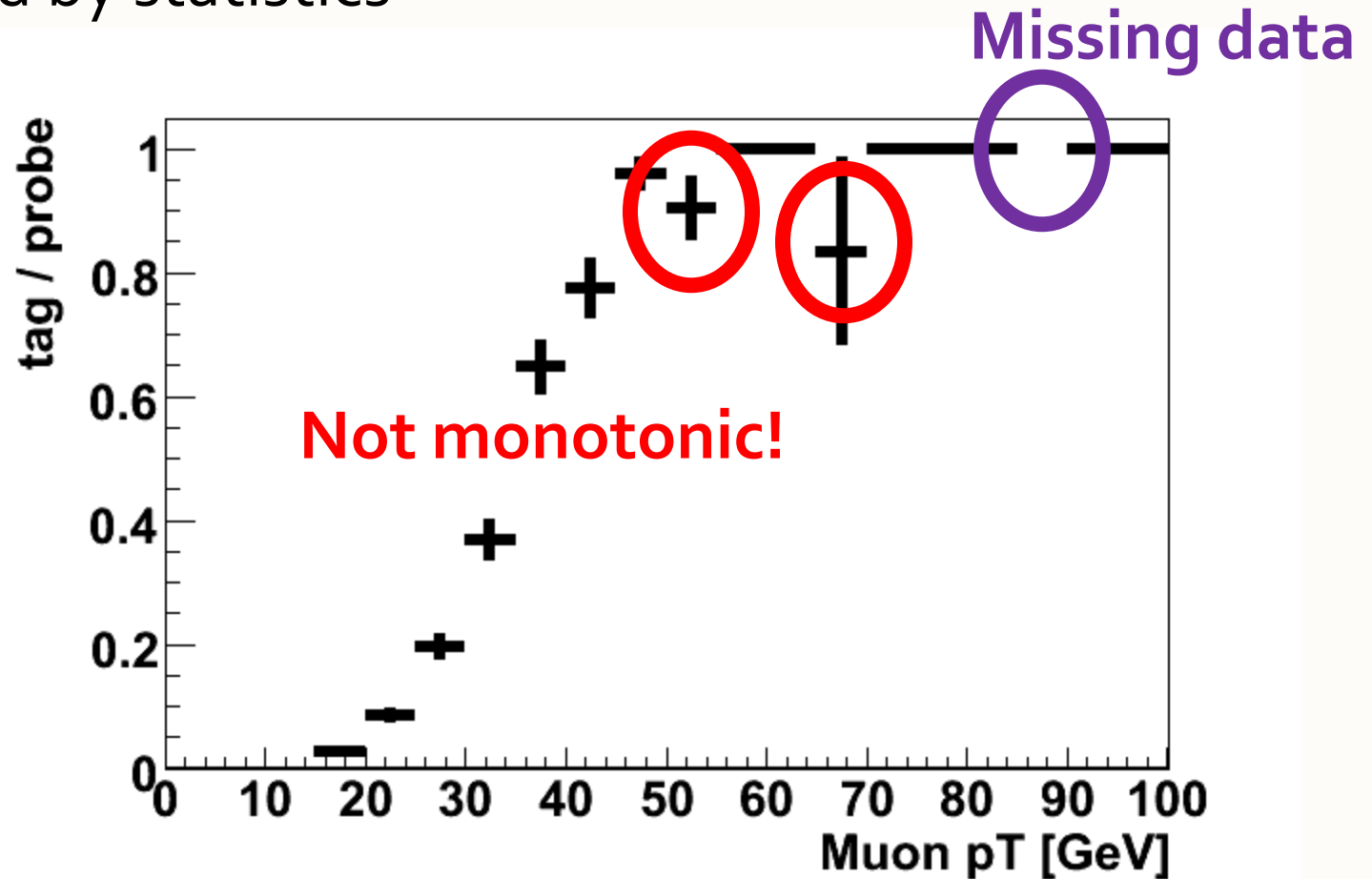
Example for a common ROOT analysis ingredient

# **FITTING**

# Fitting



Sampling "known" distribution  
Influenced by statistics

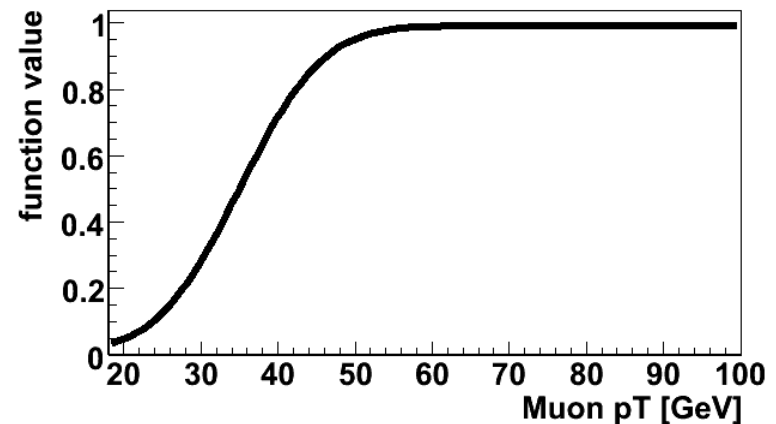


# Fit

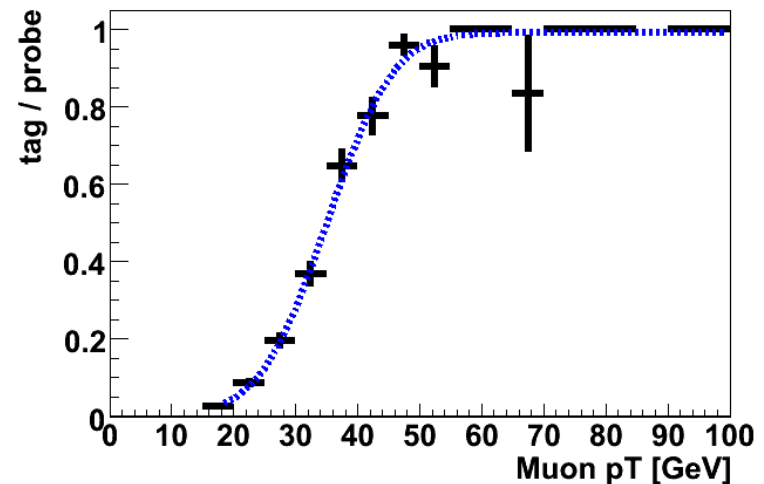


Combine our knowledge with statistics / data by fitting a distribution:

1. Find appropriate function with parameters



1. Fit function to distribution



# Fitting: The Math



Fitting = finding parameters such that

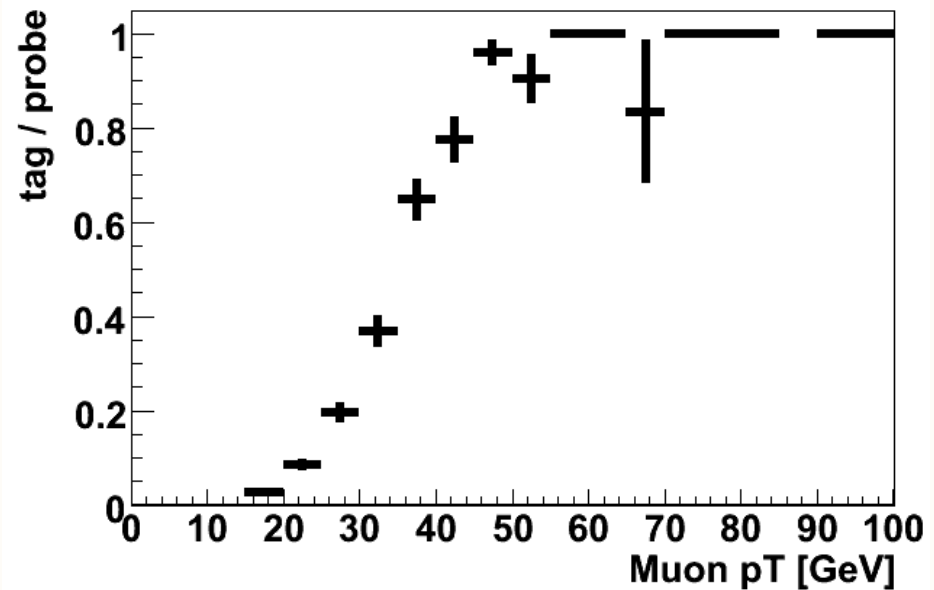
$$|f(x) - \text{hist}(x)|$$

minimal for all points  $x$  [or any similar measure]

Histogram with errors:

$$|f(x) - \text{hist}(x)| / \text{err}(x)$$

or similar



# Fitting: The Function



Finding the proper function involves:

- behavioral analysis:  
starts at 0, goes to constant, monotonic,...
- physics interpretation:  
"E proportional to  $\sin^2(\phi)$ "
- having a good knowledge of typical functions (see TMath)
- finding a good compromise between generalization ("constant") and precision ("polynomial 900<sup>th</sup> degree")

# Fitting: Parameters

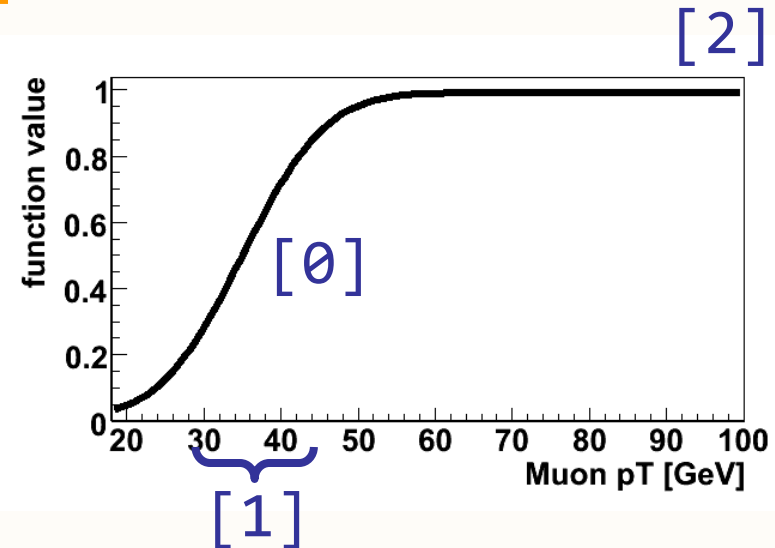
Let's take "erf"  $\text{erf}(x)/2.+0.5$

Free parameters:

[0]: x @ center of the slope

[1]:  $\frac{1}{2}$  width of the slope

[2]: maximum efficiency

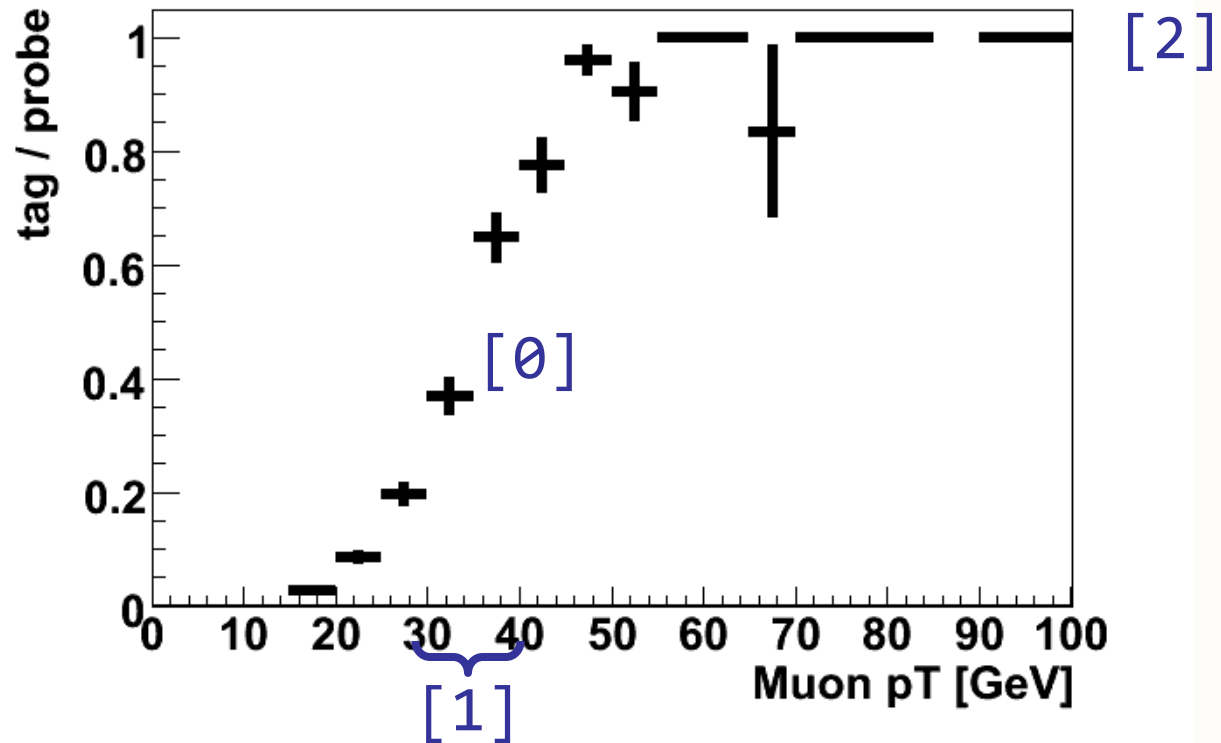


Define fit function:

```
TF1* f = new TF1("myfit",
 "(TMath::Erf((x-[0])/[1])/2.+0.5)*[2]"
 0., 100.);
```

# Fitting: Parameter Init

A must!



Sensible values:

```
f->SetParameter(0, 35.);
f->SetParameter(1, 10.);
f->SetParameter(2, 1.);
```



# Fitting Result

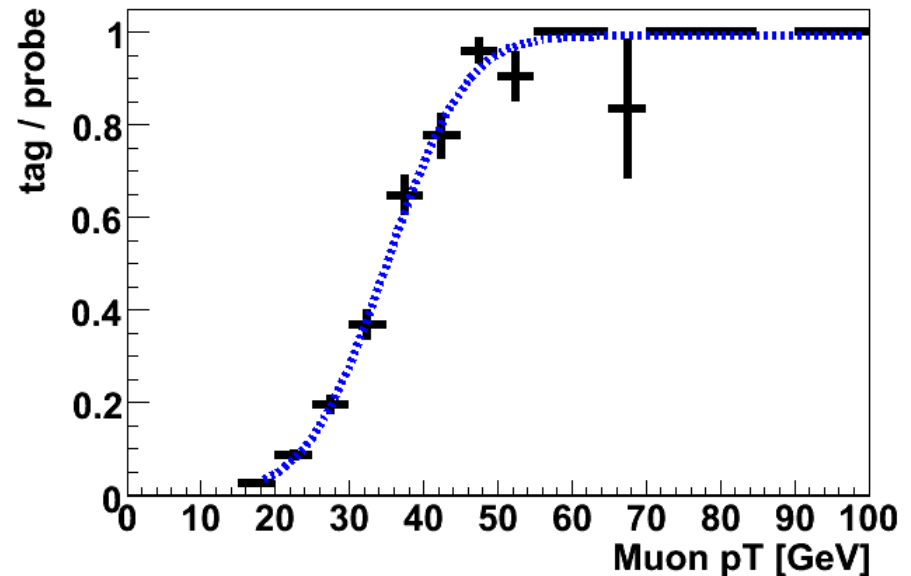
Result of `hist->Fit(f);` is printed, or use

```
f->GetParameter(0)
```

[0]: 34.9

[1]: 12.1

[2]: 0.98



which means:

```
(TMath::Erf((x-34.9)/12.1)/2.+0.5)*0.98
```

Get efficiency at pT=42GeV:

```
f->Eval(42.)
```

# Fitting: Recap



You now know

- why large samples are relevant
- what fitting is, how it works, when to do it, and how it's done with ROOT.



Bleeding Edge Physics  
with  
Bleeding Edge Computing

# **INTERACTIVE DATA ANALYSIS WITH PROOF**

# Parallel Analysis: PROOF



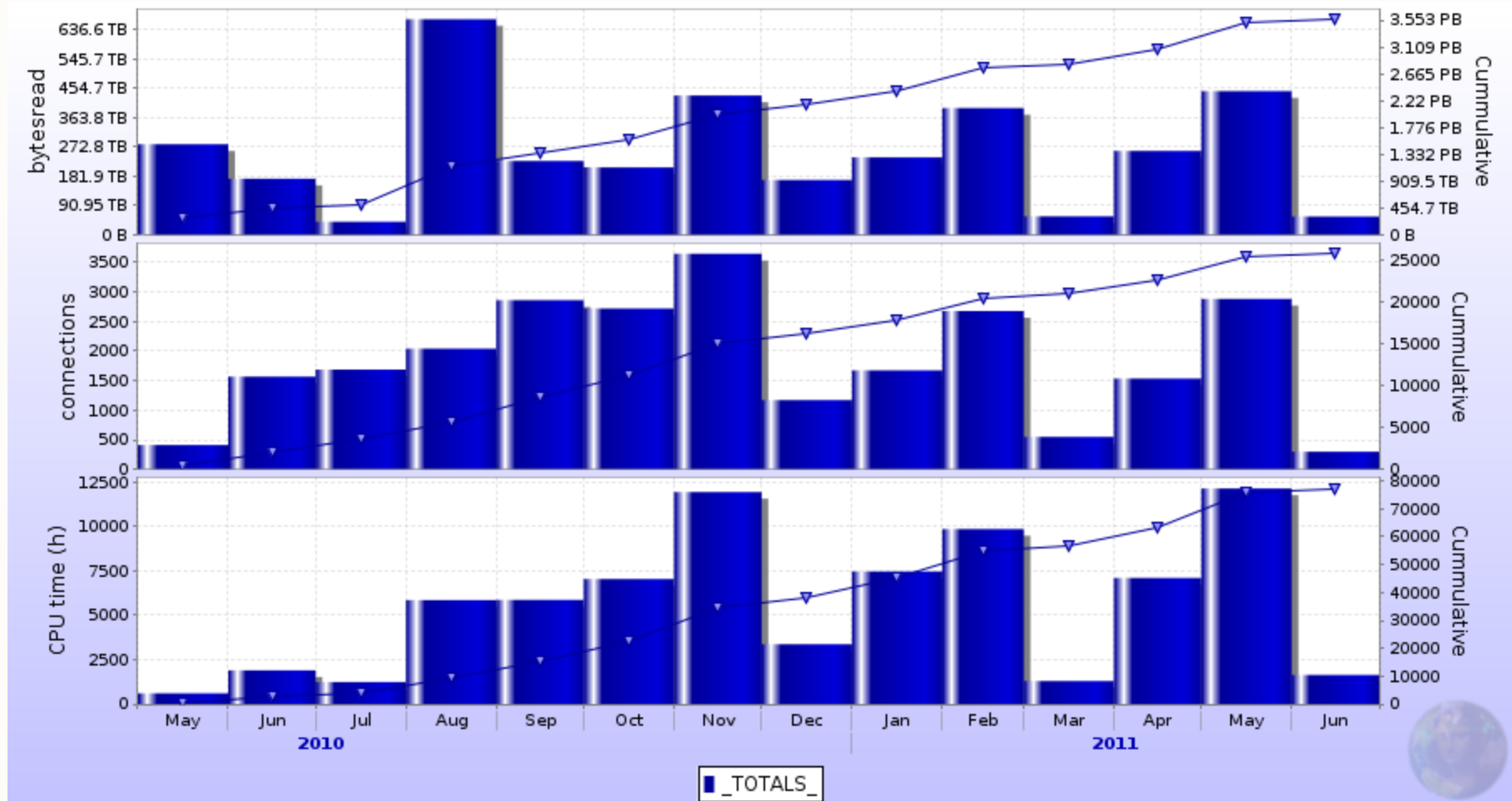
Some numbers (from Alice experiment)

- 1.5 PB ( $1.5 * 10^{15}$ ) of raw data per year
- 360 TB of ESD+AOD\* per year (20% of raw)
- One pass at 15 MB/s will take 9 months!

**Parallelism is the only way out!**

\* ESD: Event Summary Data      AOD: Analysis Object Data

# CAF Usage Statistics



# PROOF

Huge amounts of events, hundreds of CPUs

Split the job into  $N$  events / CPU!

PROOF for TSelector based analysis:

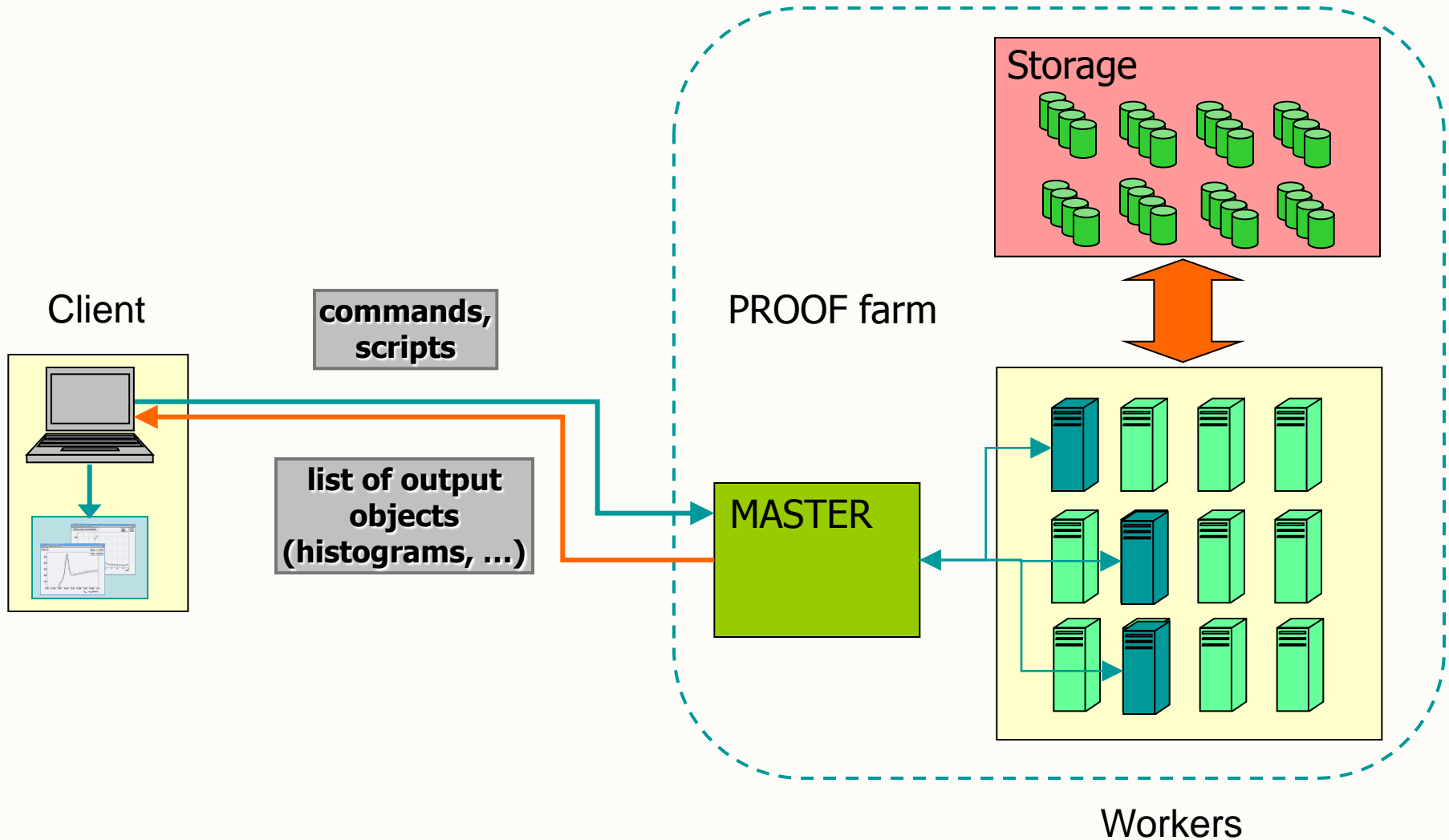
- **start** analysis locally ("client"),
- PROOF **distributes** data and code,
- lets CPUs ("workers") **run** the analysis,
- **collects** and combines (merges) data,
- shows analysis **results** locally

# Interactive!



- Start analysis
- Watch status while running
- Forgot to create a histogram?
  - Interrupt the process
  - Modify the selector
  - Re-start the analysis
- More dynamic than a batch system

# PROOF





# Scheduling



- Decides where to run which (part of) the jobs
- E.g. simple batch system
- Can autonomously split jobs into parts (“packets”)
- Involves
  - resource management (CPU, I/O, memory)
  - data locality
  - priorities (jobs / users)
  - and whatever other criteria are deemed relevant
- Often optimizing jobs’ distribution towards overall goal: maximum CPU utilization (Grid), minimum time to result (PROOF)

# Packetizer Role and Goals



- Distributes units of work ("packets") to workers
- Grid's packet:  $\geq 1$  file
- Result arrives when last resource has processed last file:

$$t = t_{\text{init}} + \max_{\text{jobs}} (R_i \cdot N_i^{\text{files}}) + t_{\text{final}}$$

$t_{\text{init}}, t_{\text{final}}$ : time to initialize / finalize the jobs

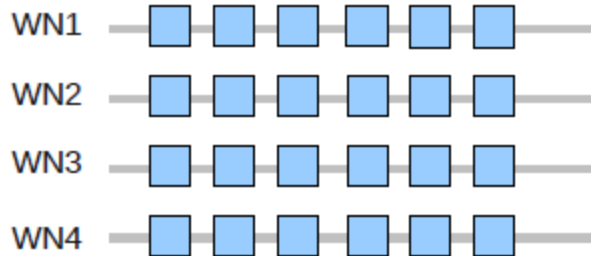
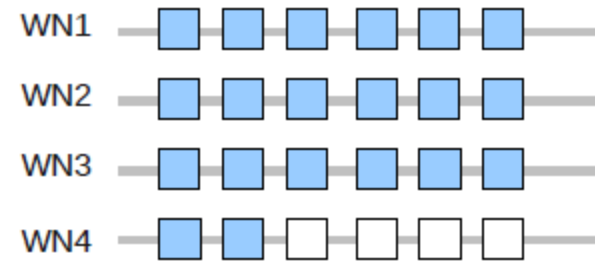
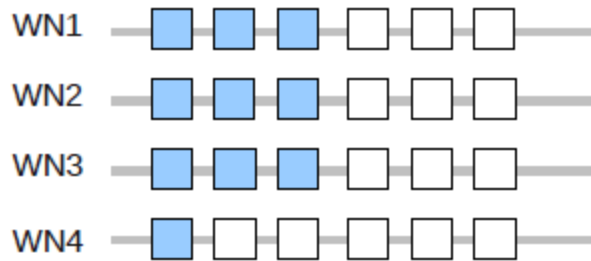
$R_i$ : processing rate of job  $i$

$N_i^{\text{files}}$ : number of files for job  $i$

- Result:
  - slowest job defines running time
  - large tail in CPU utilization versus time

# Static...

- Example: 24 files on 4 worker nodes, one under-performing



The slowest worker node sets the processing time

# PROOF's Dynamic Packetizer



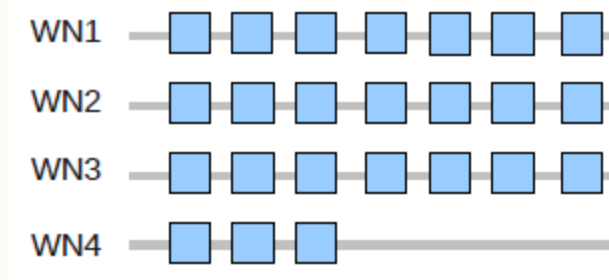
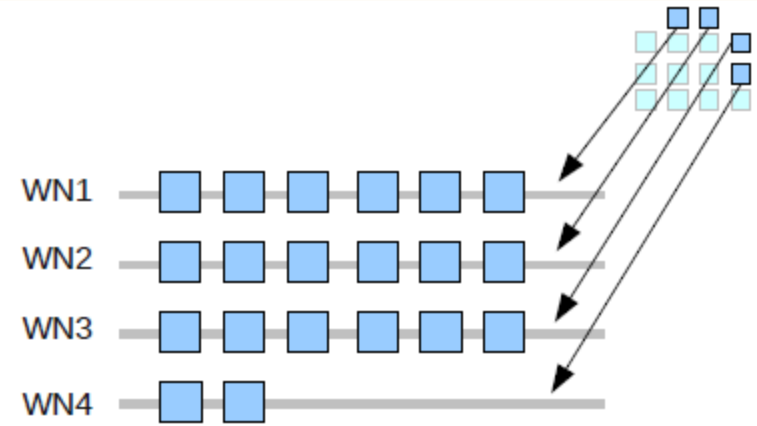
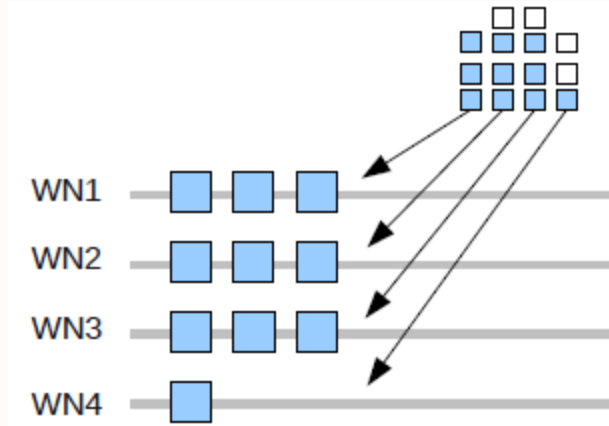
- PROOF packetizer's goal: results as early as possible
- All workers should finish at the same time:

$$t = t_{\text{init}} + \max_{\text{jobs}} (R_i \cdot N_i^{\text{files}}) + t_{\text{final}}$$

ideally,  $R_i \cdot N_i^{\text{files}}$  equal for all jobs

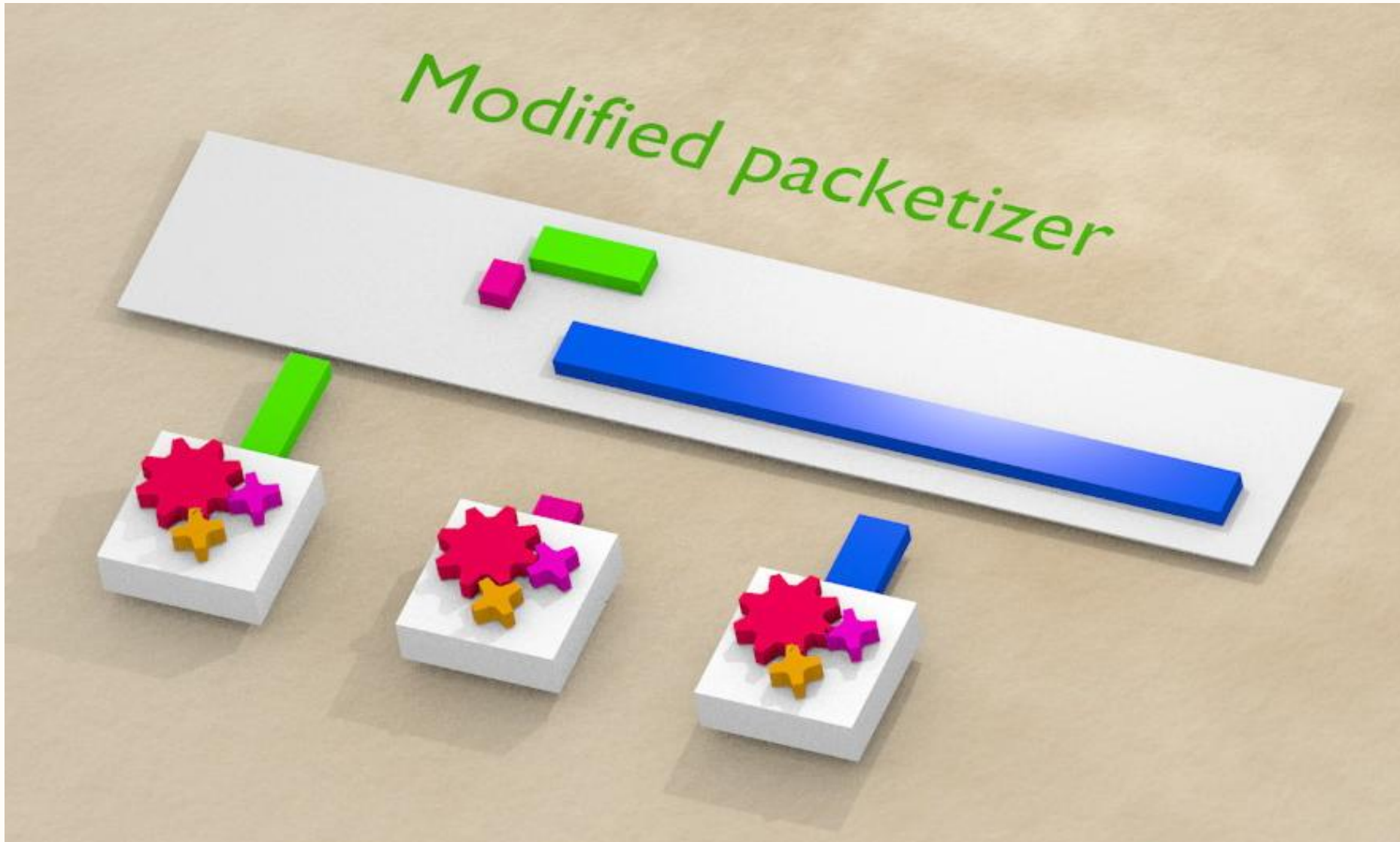
- Cannot reliably predict performance ( $R_i$ ) of workers
  - job interaction, e.g. number of jobs accessing the same disk
  - CPU versus I/O duty of jobs
- Instead: update prediction based on real-time past performance while running
- Pull architecture: workers ask for new packets

# Dynamic Packet Distribution



The slowest worker node gets less work to do: the processing time is less affected by its under performance

# PROOF Packetizer Live



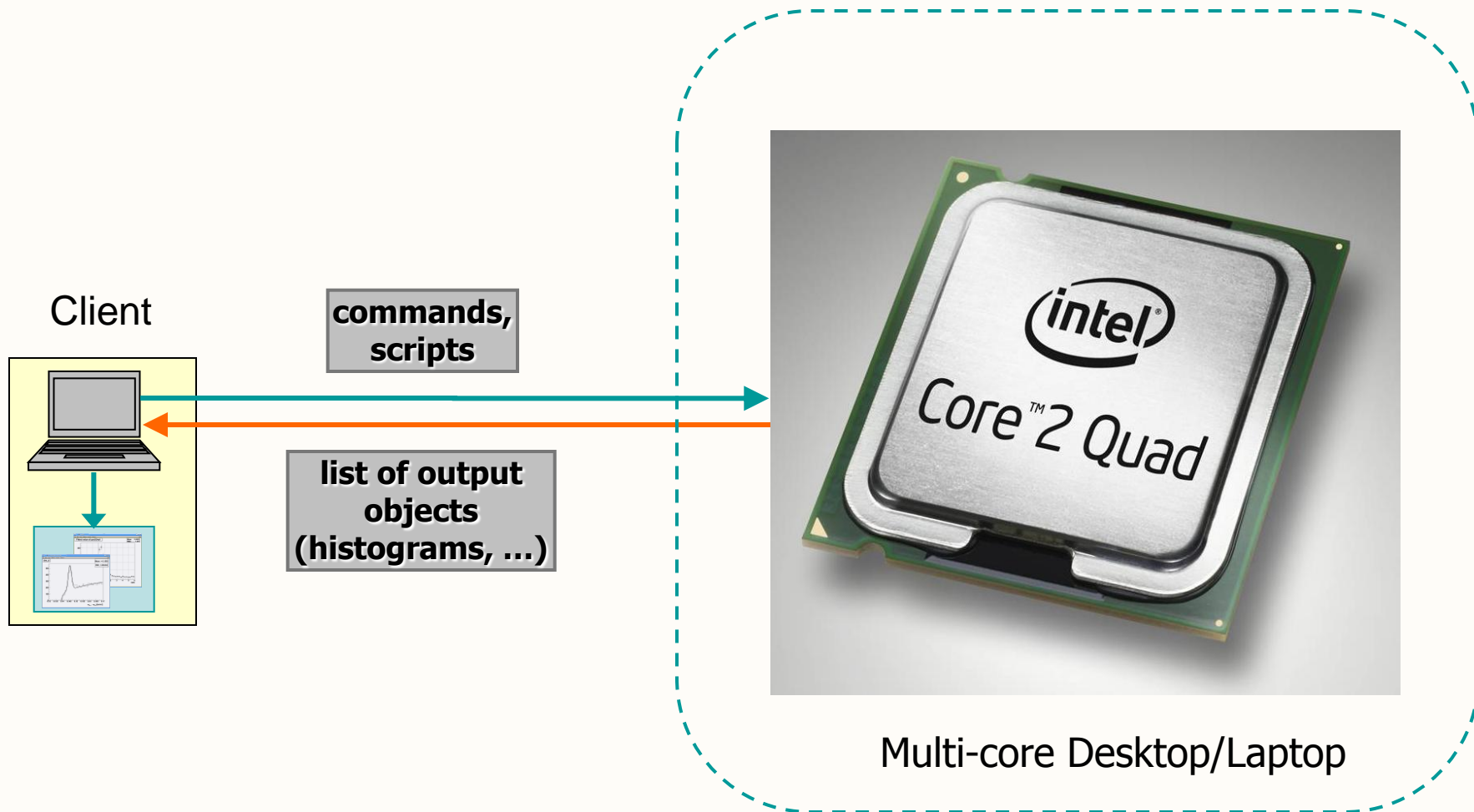
# Creating a session

To create a PROOF session from the ROOT prompt, just type:

```
TProof::Open("master")
```

where "master" is the hostname of the master machine on the PROOF cluster

# PROOF Lite





# What is PROOF Lite?



- PROOF optimized for single many-core machines
- Zero configuration setup
  - No config files and no daemons
- Like PROOF it can exploit fast disks, SSD's, lots of RAM, fast networks and fast CPU's
- If your code works on PROOF, then it works on PROOF Lite and vice versa

# Creating a session

To create a PROOF Lite session from the ROOT prompt, just type:

```
TProof::Open("")
```

Then you can use your multicore computer as a PROOF cluster!

# PROOF Analysis



- Example of local TChain analysis

```
// Create a chain of trees
root[0] TChain *c = new TChain("myTree");
root[1] c->Add("http://www.any.where/file1.root");
root[2] c->Add("http://www.any.where/file2.root");

// MySelector is a TSelector
root[3] c->Process("MySelector.C+");
```



# PROOF Analysis



- Same example with PROOF

```
// Create a chain of trees
root[0] TChain *c = new TChain("myTree");
root[1] c->Add("http://www.any.where/file1.root");
root[2] c->Add("http://www.any.where/file2.root");

// Start PROOF and tell the chain to use it
root[3] TProof::Open("");
root[4] c->SetProof();

// Process goes via PROOF
root[5] c->Process("MySelector.C+");
```

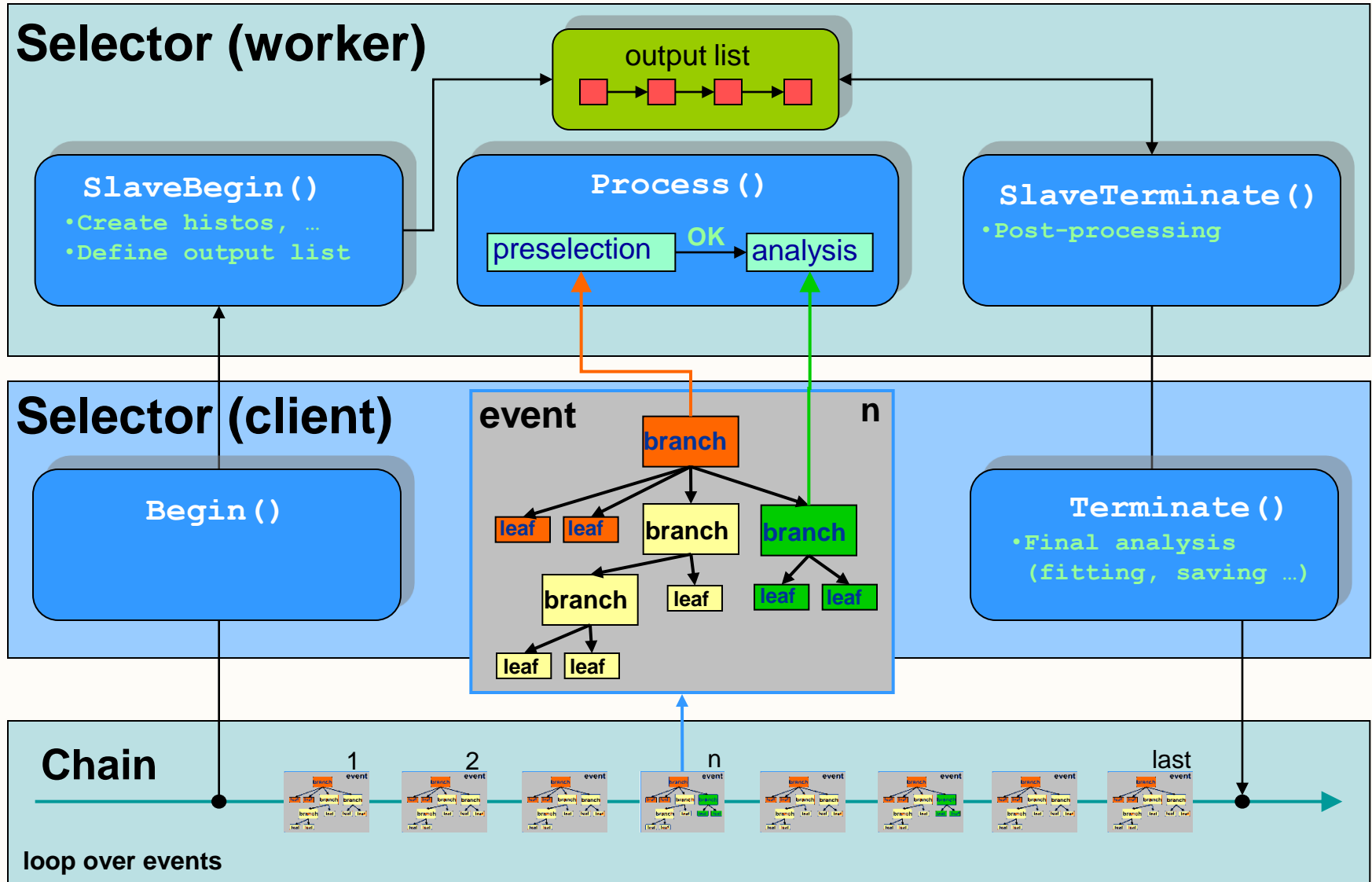


# TSelector & PROOF



- **Begin()** called on the **client** only
- **SlaveBegin()** called on each **worker**: create histograms
- **SlaveTerminate()** rarely used; post processing of partial results before they are sent to master and merged
- **Terminate()** runs on the **client**: save results, display histograms, ...

# PROOF Analysis



# Output List (result of the query)



- Each worker has a partial output list
- Objects have to be added to the list in TSelector::SlaveBegin() e.g.:

```
fHist = new TH1F("h1", "h1", 100, -3., 3.);
fOutput->Add(fHist);
```

- At the end of processing the output list gets sent to the master
- The Master merges objects and returns them to the client. Merging is e.g. "Add()" for histograms, appending for lists and trees

# Example



```
void MySelector::SlaveBegin(TTree *tree) {
 // create histogram and add it to the output list
 fHist = new TH1F("MyHist","MyHist",40,0.13,0.17);
 GetOutputList()->Add(fHist);
}

Bool_t MySelector::Process(Long64_t entry) {
 my_branch->GetEntry(entry); // read branch
 fHist->Fill(my_data); // fill the histogram
 return kTRUE;
}

void MySelector::Terminate() {
 fHist->Draw(); // display histogram
}
```



# Results



At the end of `Process()`, the output list is accessible via `gProof->GetOutputList()`

```
// Get the output list
root[0] TList *output = gProof->GetOutputList();
// Retrieve 2D histogram "h2"
root[1] TH2F *h2 = (TH2F*)output->FindObject("h2");
// Display the histogram
root[2] h2->Draw();
```

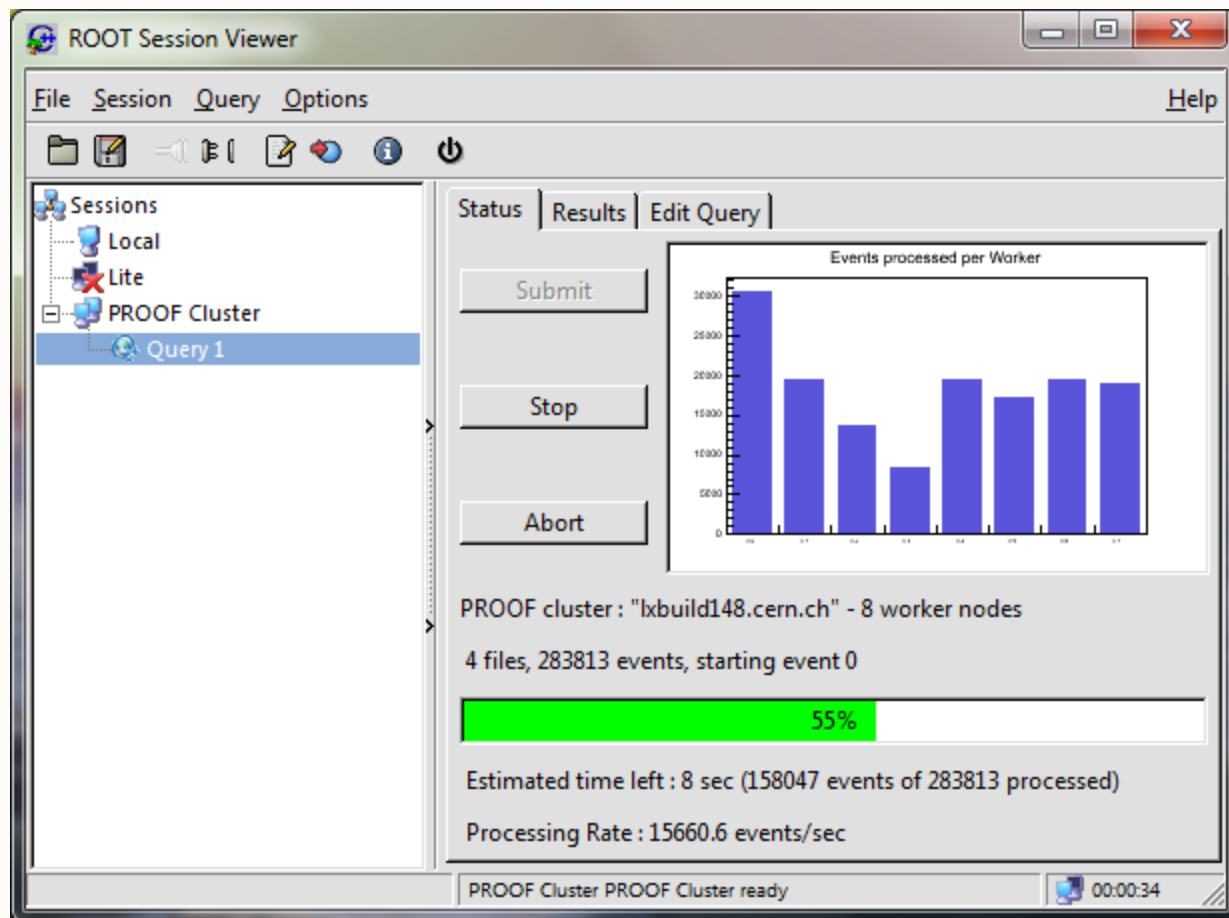
# PROOF GUI Session



Starting a PROOF GUI session is trivial:

`TProof::Open()`

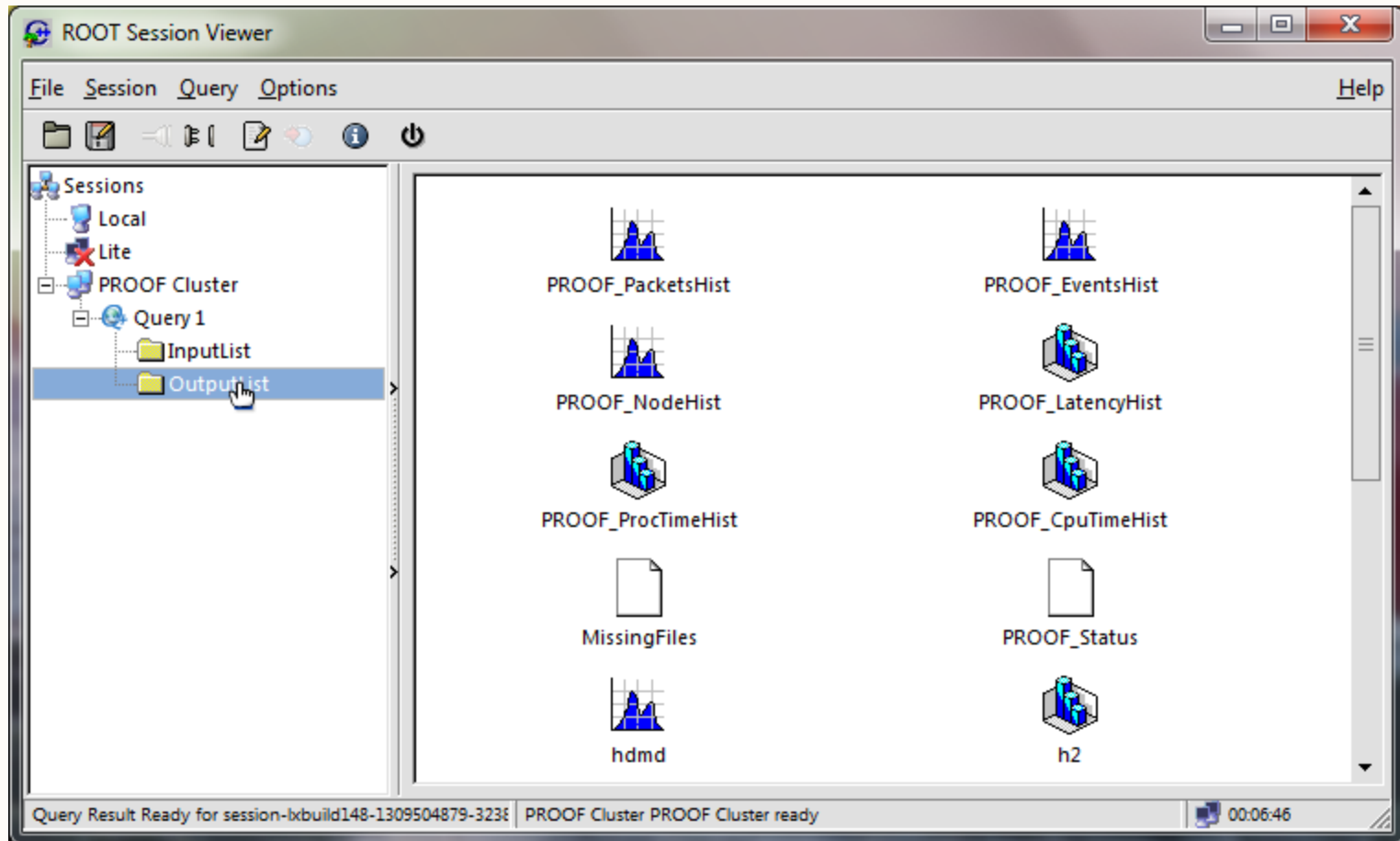
Opens GUI:



# PROOF GUI Session – Results



Results accessible via TSessionViewer, too:



# PROOF Documentation



Documentation available online at

<http://root.cern.ch/drupal/content/proof>

But of course you need a little cluster of CPUs

Like your multi-core  
game console!



# Summary

You've learned:

- analyzing a TTree can be easy and efficient
- integral part of physics is counting
- ROOT provides histogramming and fitting
- $> 1$  CPU: use PROOF!

Looking forward to hearing from you:

- as a user (help! bug! suggestion!)
- and as a developer!